



<http://algs4.cs.princeton.edu>

## 4.1 UNDIRECTED GRAPHS

---

- ▶ *introduction*
- ▶ *graph API*
- ▶ *depth-first search*
- ▶ *breadth-first search*
- ▶ *connected components*
- ▶ *challenges*



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بصير دبل → عزمه →

## 4.1 UNDIRECTED GRAPHS

ما يكون فيه اتجاهات →  
يحسب من الطرفين رادح وحاي

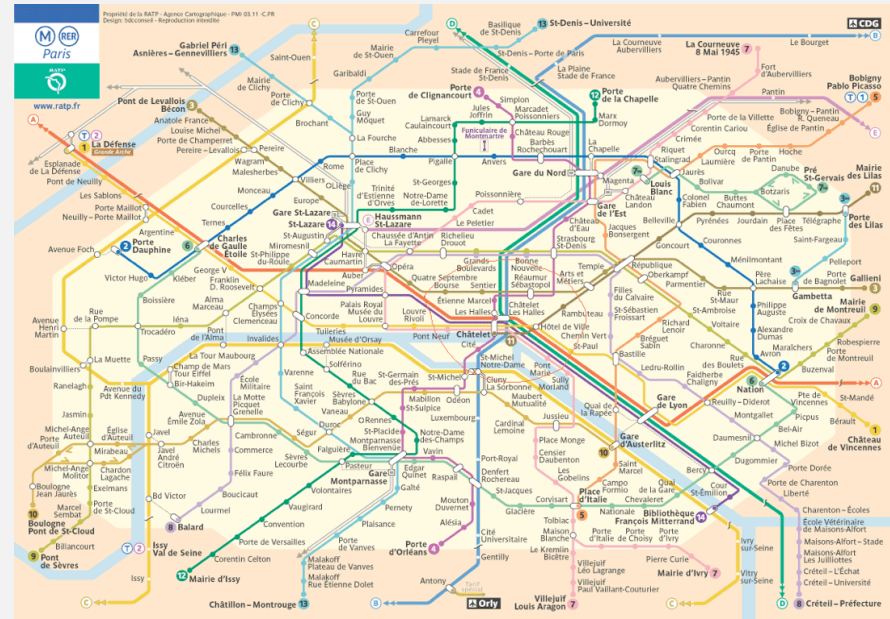
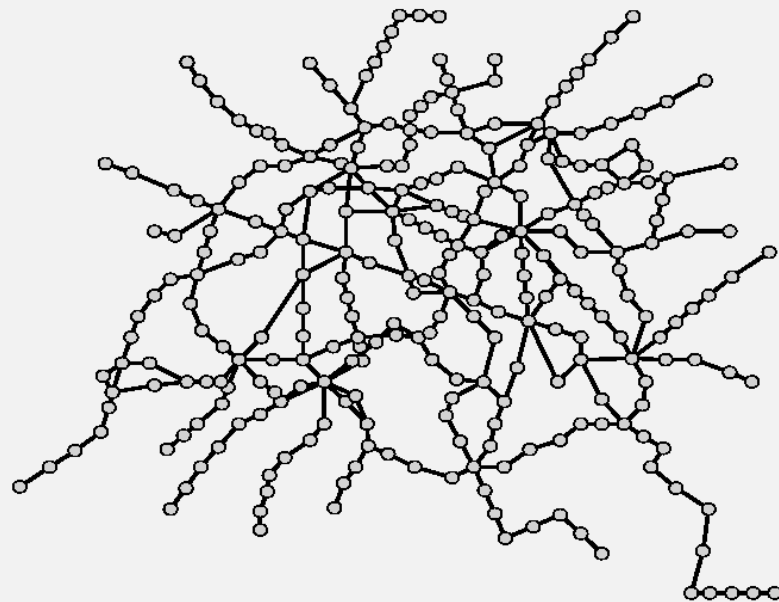
- ▶ *introduction*
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# Undirected graphs

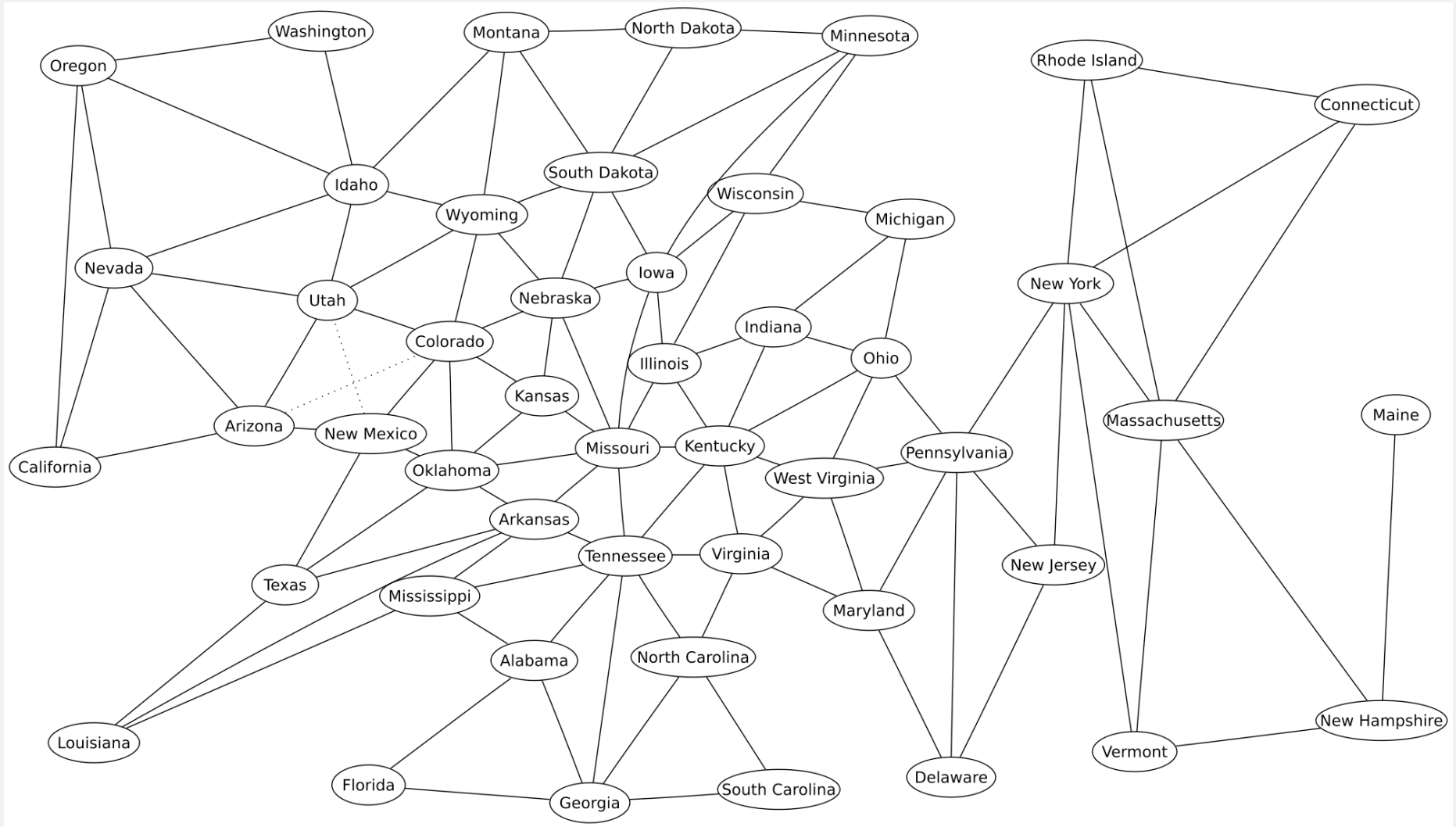
Graph. Set of <sup>v</sup>vertices connected pairwise by edges. <sup>تتصلب من الجهتين</sup>

## Why study graph algorithms?

- Thousands of practical applications.
- Hundreds of graph algorithms known.
- Interesting and broadly useful abstraction.
- Challenging branch of computer science and discrete math.

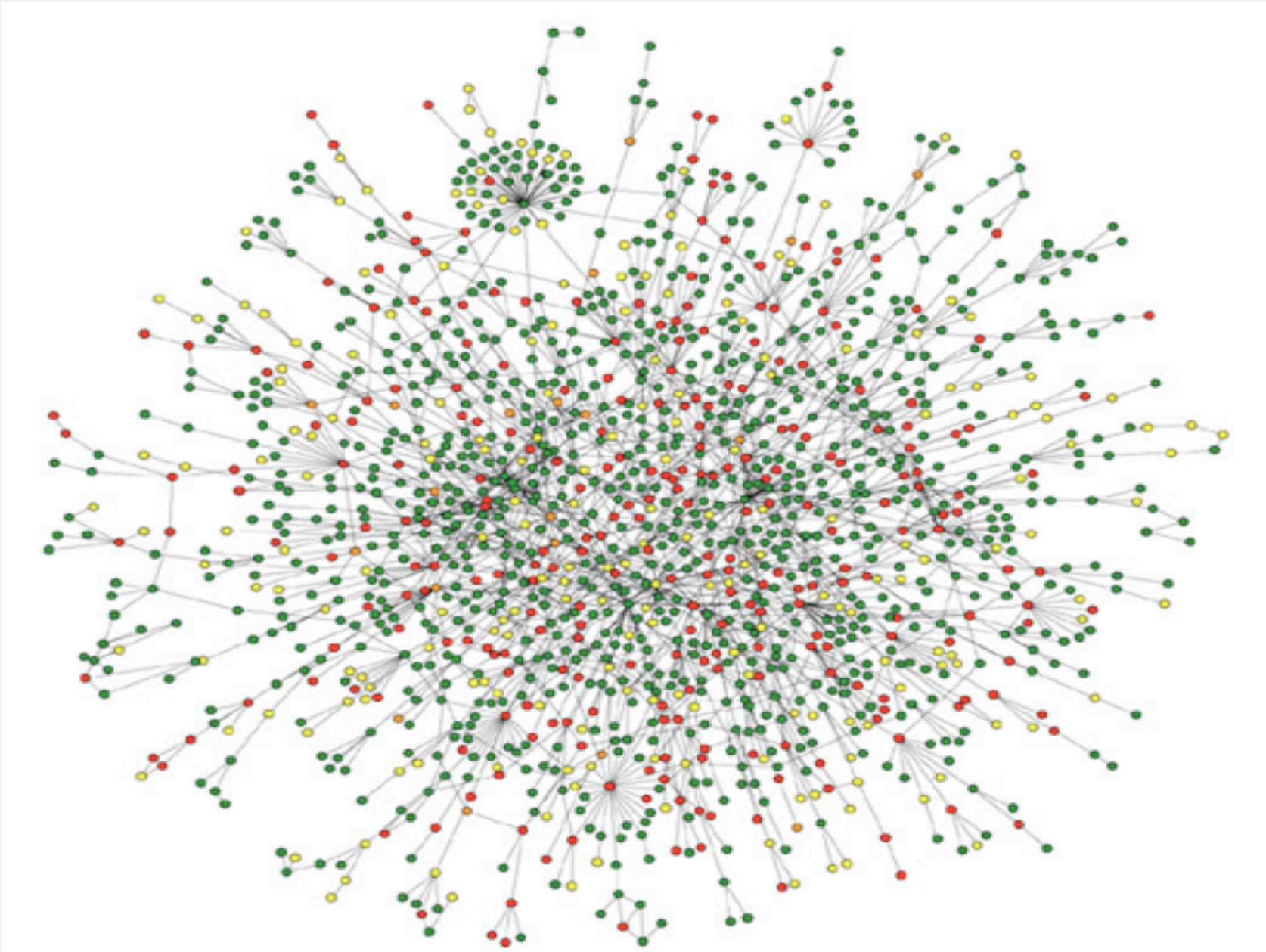


# Border graph of 48 contiguous United States



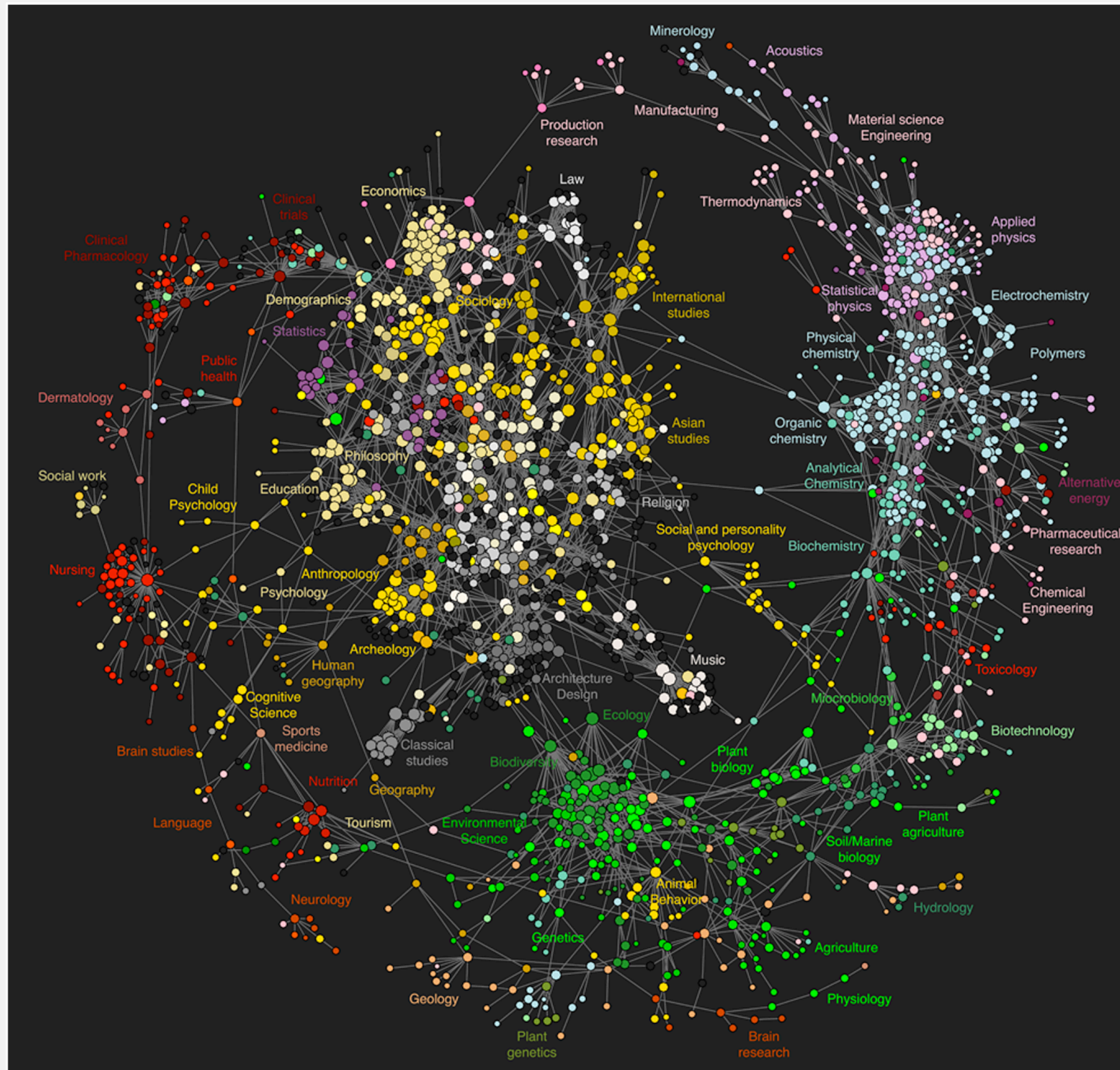
# Protein-protein interaction network

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Reference: Jeong et al, Nature Review | Genetics

# Map of science clickstreams



<http://www.plosone.org/article/info:doi/10.1371/journal.pone.0004803>



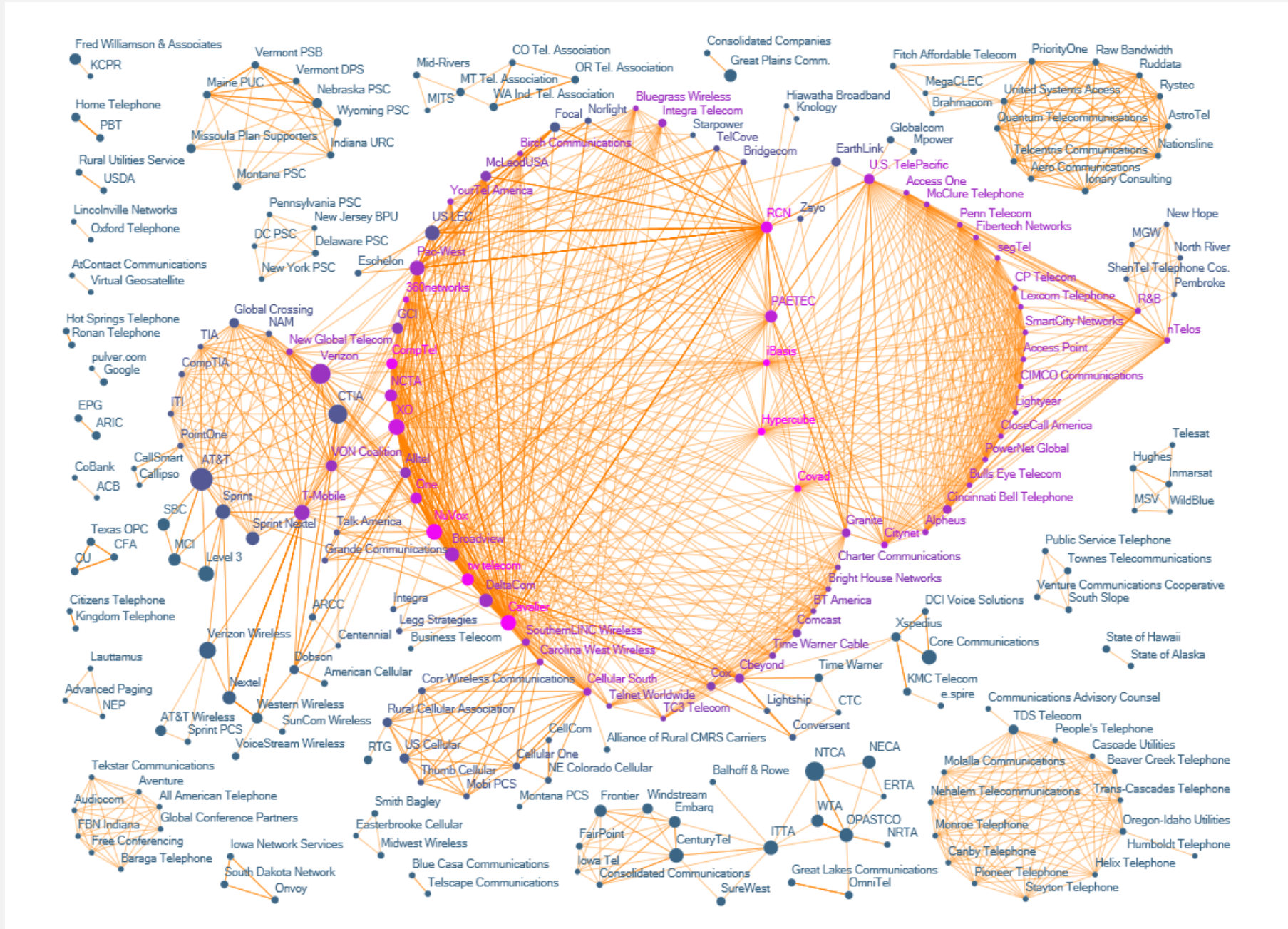
# 10 million Facebook friends

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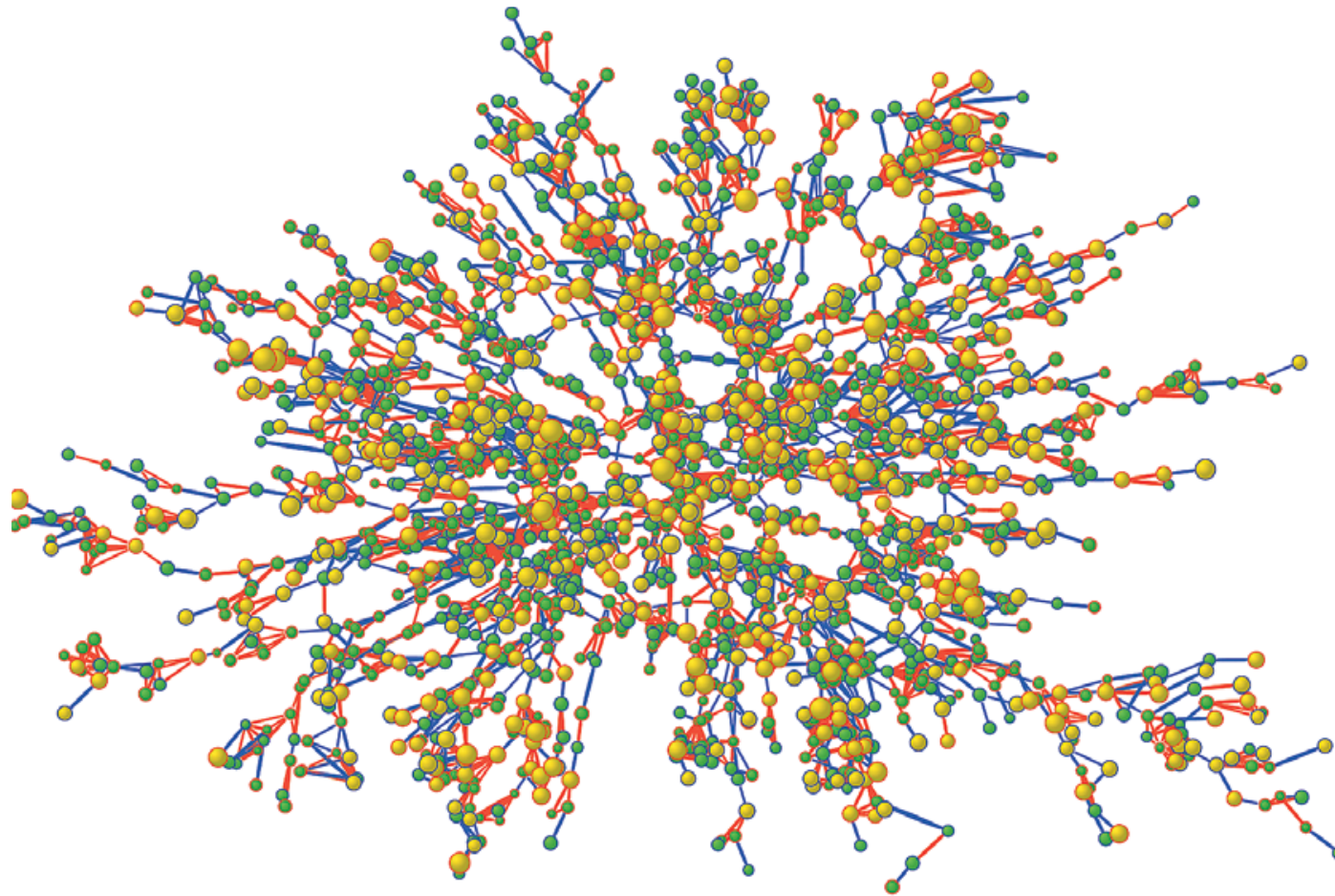
"Visualizing Friendships" by Paul Butler

# The evolution of FCC lobbying coalitions



“The Evolution of FCC Lobbying Coalitions” by Pierre de Vries in JoSS Visualization Symposium 2010

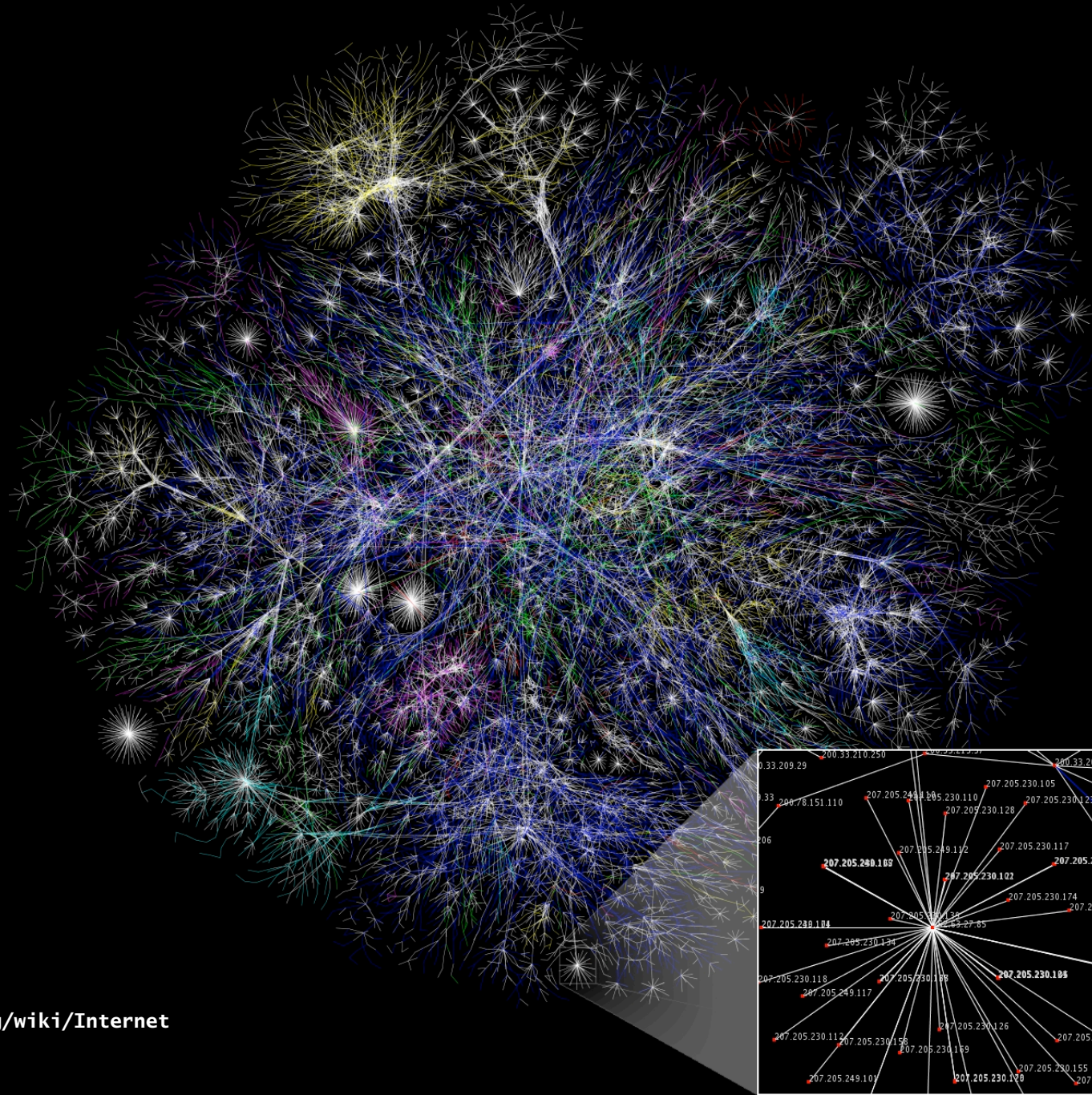
# Framingham heart study



**Figure 1.** Largest Connected Subcomponent of the Social Network in the Framingham Heart Study in the Year 2000.

Each circle (node) represents one person in the data set. There are 2200 persons in this subcomponent of the social network. Circles with red borders denote women, and circles with blue borders denote men. The size of each circle is proportional to the person's body-mass index. The interior color of the circles indicates the person's obesity status: yellow denotes an obese person (body-mass index,  $\geq 30$ ) and green denotes a nonobese person. The colors of the ties between the nodes indicate the relationship between them: purple denotes a friendship or marital tie and orange denotes a familial tie.

# The Internet as mapped by the Opte Project



<http://en.wikipedia.org/wiki/Internet>

# Graph applications

---

graph	vertex	edge
<b>communication</b>	telephone, computer	fiber optic cable
<b>circuit</b>	gate, register, processor	wire
<b>mechanical</b>	joint	rod, beam, spring
<b>financial</b>	stock, currency	transactions
<b>transportation</b>	intersection	street
<b>internet</b>	class C network	connection
<b>game</b>	board position	legal move
<b>social relationship</b>	person	friendship
<b>neural network</b>	neuron	synapse
<b>protein network</b>	protein	protein-protein interaction
<b>molecule</b>	atom	bond

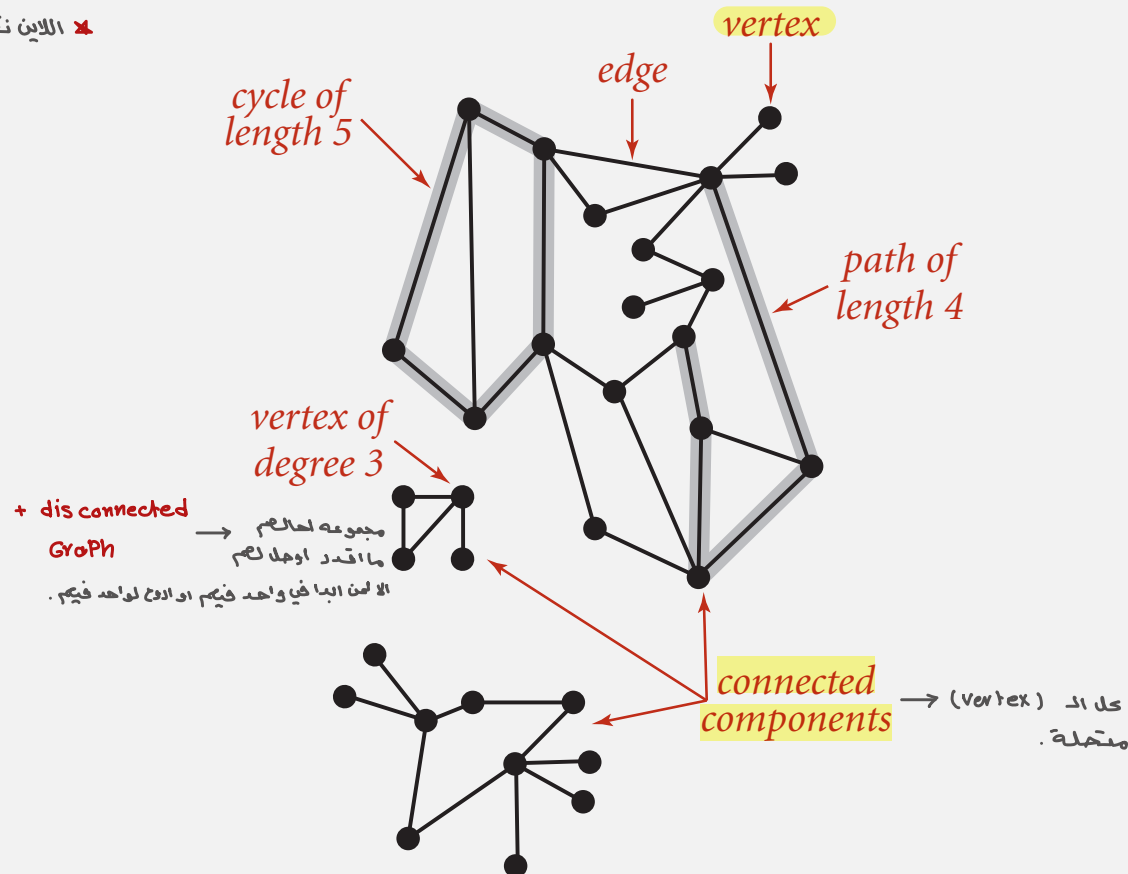
# Graph terminology

**Path.** <sup>متوابع</sup> Sequence of vertices connected by edges. → الطريق الي بتتصيه علشان

**Cycle.** Path whose first and last vertices are the same. → لقوليين (Path) ثانيين  
البدأ من نقطة والبع لنفس النقطة.

Two vertices are **connected** if there is a path between them.

✘ اللابن نفسه يحسب رايح جاي



# Some graph-processing problems

---

problem	description
<b>s-t path</b>	<i>Is there a path between <math>s</math> and <math>t</math> ?</i>
<b>shortest s-t path</b>	<i>What is the shortest path between <math>s</math> and <math>t</math> ?</i>
<b>cycle</b>	<i>Is there a cycle in the graph ?</i>
<b>Euler cycle</b>	<i>Is there a cycle that uses each edge exactly once ?</i>
<b>Hamilton cycle</b>	<i>Is there a cycle that uses each vertex exactly once ?</i>
<b>connectivity</b>	<i>Is there a way to connect all of the vertices ?</i>
<b>biconnectivity</b>	<i>Is there a vertex whose removal disconnects the graph ?</i>
<b>planarity</b>	<i>Can the graph be drawn in the plane with no crossing edges ?</i>
<b>graph isomorphism</b>	<i>Do two adjacency lists represent the same graph ?</i>

**Challenge.** Which graph problems are easy? difficult? intractable?



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## 4.1 UNDIRECTED GRAPHS → ما فيها مؤثر ونسبها (diagonal) . → العلاقة رايحه باية.

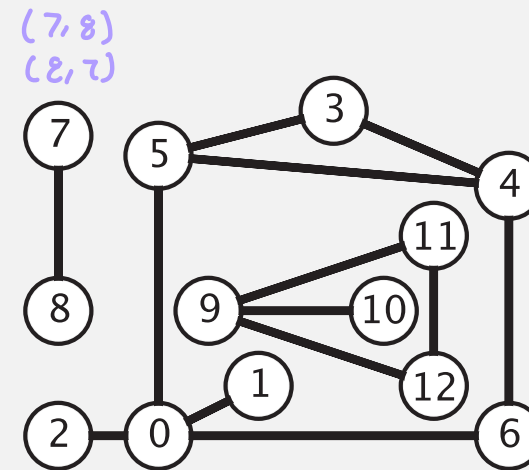
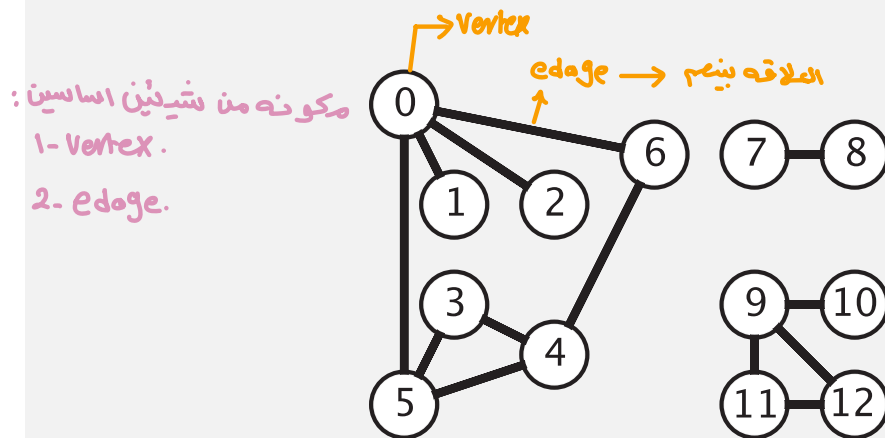
- ▶ *introduction*
- ▶ *graph API*
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- ▶ *breadth-first search*
- ▶ *connected components*
- ▶ *challenges*

# Graph representation

Graph drawing. Provides intuition about the structure of the graph.

ما عندي مشكله بطريقه الرسم  
اصح شي . الاين ما انساها وال (Vertex).

كم رسم يتطلع من  
الرقم او ال Vertic .  
degrec:



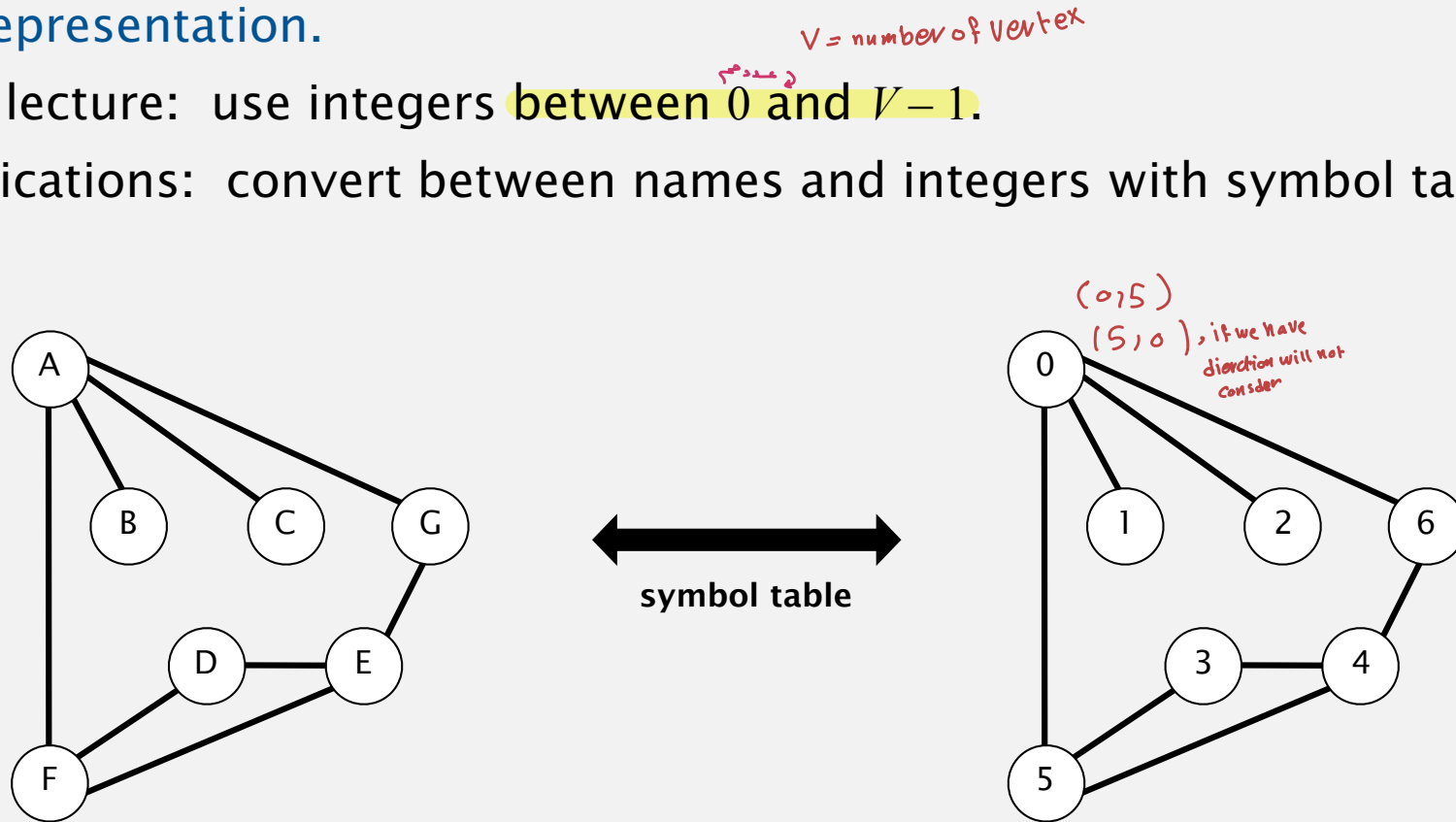
two drawings of the same graph

Caveat. Intuition can be misleading.

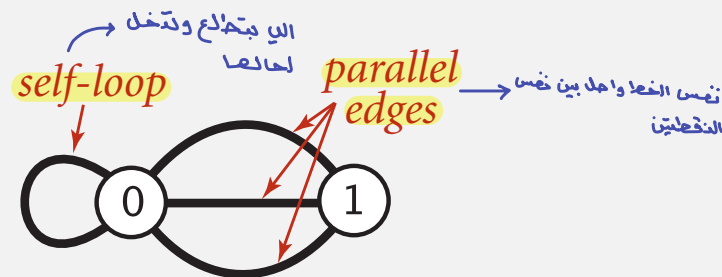
# Graph representation

## Vertex representation.

- This lecture: use integers **between 0 and  $V-1$** .
- Applications: convert between names and integers with symbol table.



## Anomalies.



# Graph API

```
public class Graph
```

```
    Graph(int V)
```

*create an empty graph with V vertices*

```
    Graph(In in)
```

*create a graph from input stream*

```
    void addEdge(int v, int w)
```

*add an edge v-w*

```
    Iterable<Integer> adj(int v)
```

*vertices adjacent to v*

```
    int V()
```

*number of vertices*

```
    int E()
```

*number of edges*

*عدد الاضلاع المتصلة مع الـ vertex*

```
// degree of vertex v in graph G  
public static int degree(Graph G, int v)  
{  
    int degree = 0;  
    for (int w : G.adj(v))  
        degree++;  
    return degree;  
}
```

# Graph API: sample client

## Graph input format.

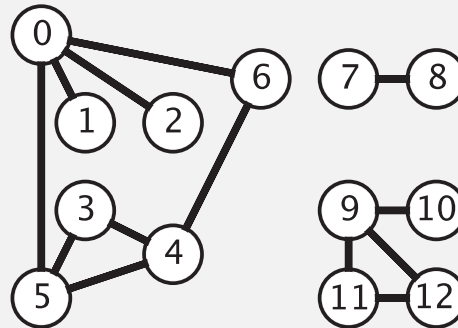
**tinyG.txt**

V → 13  
 13 ← E

```

0 5
4 3
0 1
9 12
6 4
5 4
0 2
11 12
9 10
0 6
7 8
9 11
5 3
  
```

adjacent : *العلة الى اقدر انتقل  
 باد vertex الثانيه خلالها.*



*صاراح اجمع الاقرب من (5, 6)  
 لانه (undirected)  
 لو كنت شاكه اي نوع (by default):  
 directed الا اذا كتبت  
 بالموال (undirected)*

```

% java Test tinyG.txt
0-6
0-2
0-1
0-5
1-0
2-0
3-5
3-4
:
12-11
12-9
  
```

*directed*

*\* donmeic dato  
 how many time edge:  
 o(e)*

```

In in = new In(args[0]);
Graph G = new Graph(in);

for (int v = 0; v < G.V(); v++)
  for (int w : G.adj(v))
    StdOut.println(v + "-" + w);
  
```

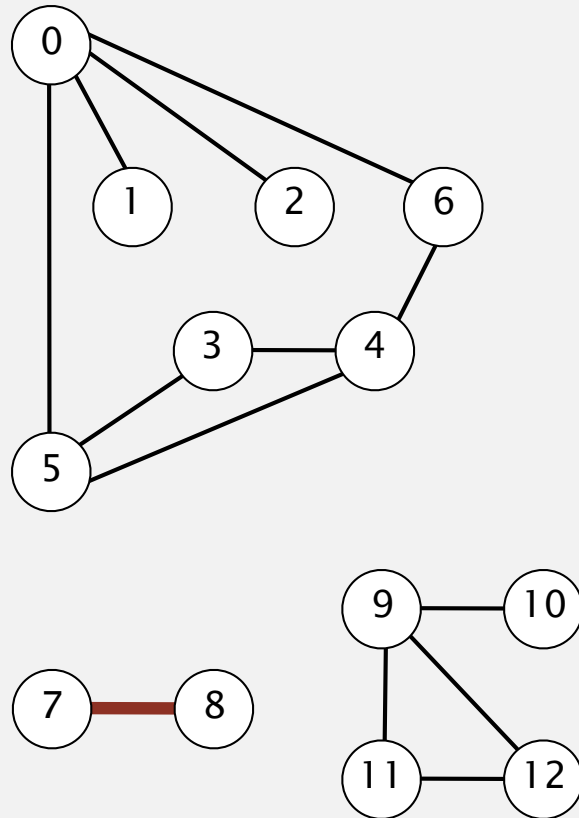
← read graph from input stream

← print out each edge (twice)

# Graph representation: **set of edges**

Maintain a list of the edges (**linked list or array**).

كم خط طالع  
منها  
degree:



اللاين اجنر لان كل واحد مكرر

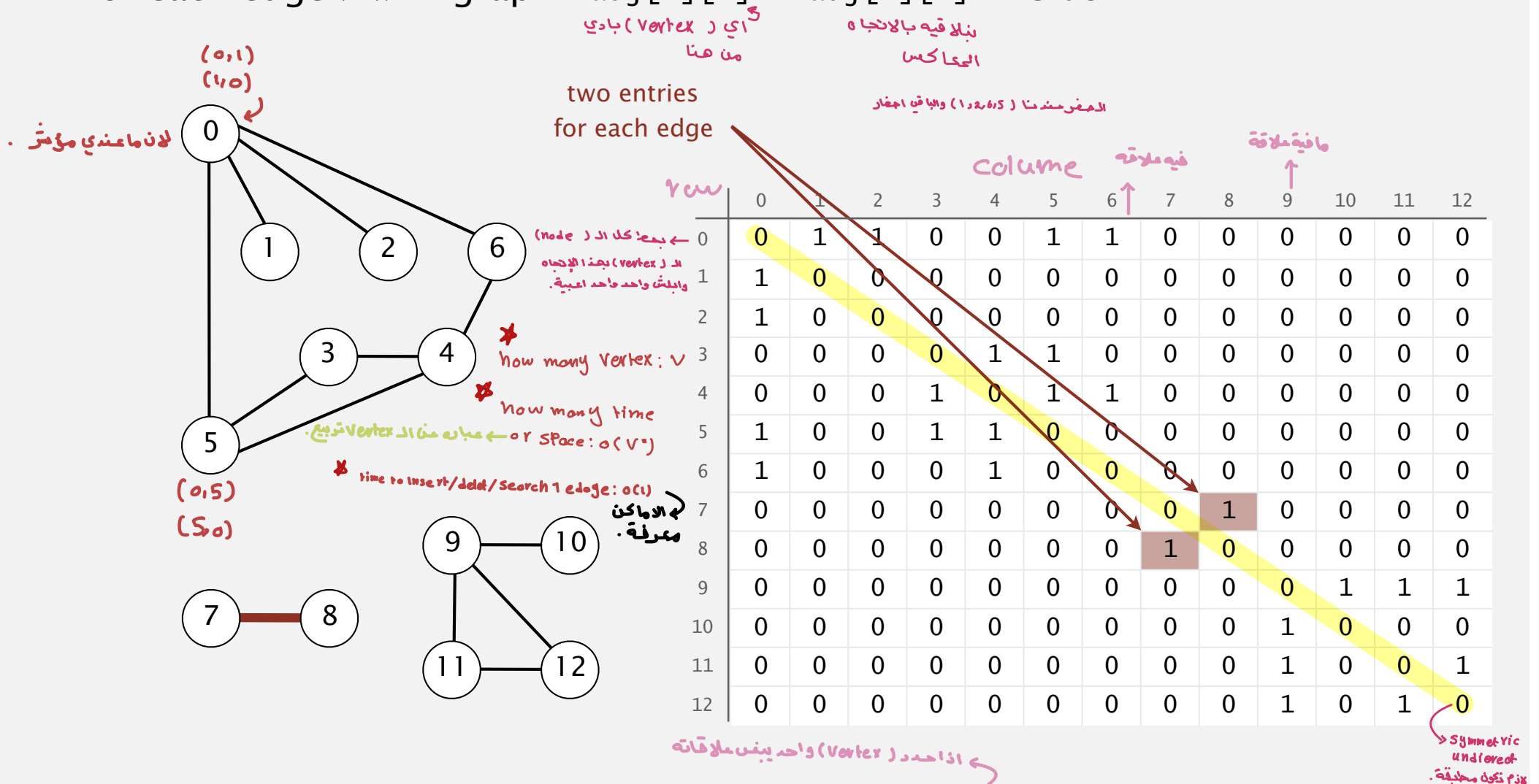
0	1
0	2
0	5
0	6
3	4
3	5
4	5
4	6
7	8
9	10
9	11
9	12
11	12

Q. How long to iterate over vertices adjacent to  $v$  ?

# Graph representation: adjacency matrix

Maintain a **two-dimensional  $V$ -by- $V$  boolean array;**

for each edge  $v-w$  in graph:  $adj[v][w] = adj[w][v] = true$ .



Q. How long to iterate over vertices adjacent to  $v$ ?  $O(V)$

How long to iterate over all vertices:  $O(V^2)$  → لأن نمر عليها كاملة.

# Graph representation: adjacency lists like hash table Same like SParte CHine in hash table.

Maintain vertex-indexed array of lists.

degree = edge عدد ال  
الي خالغ منها كم سم خالغ منها

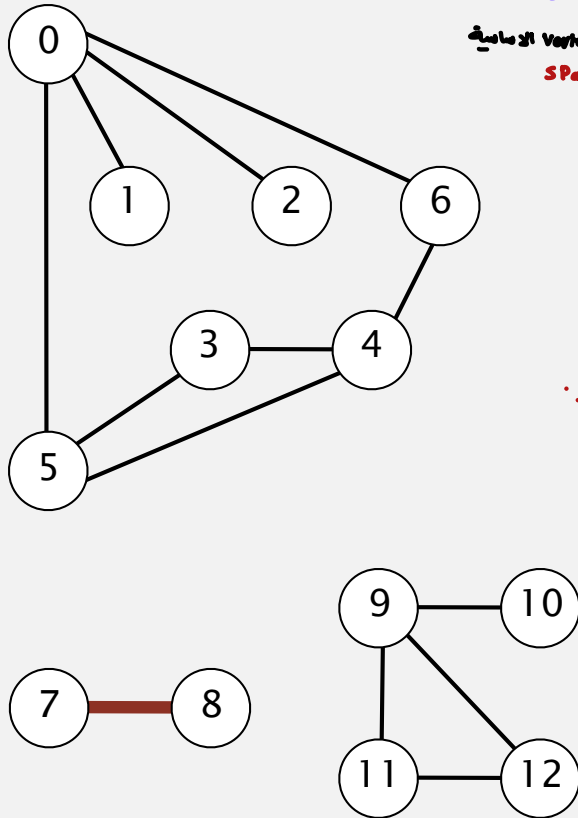
\* undirected : العلاقات لازم  
تكرر مرتين

Ex: (4,5)  
(5,4)

عدد ال vertex الاساسية  
Space:  $O(V+E)$

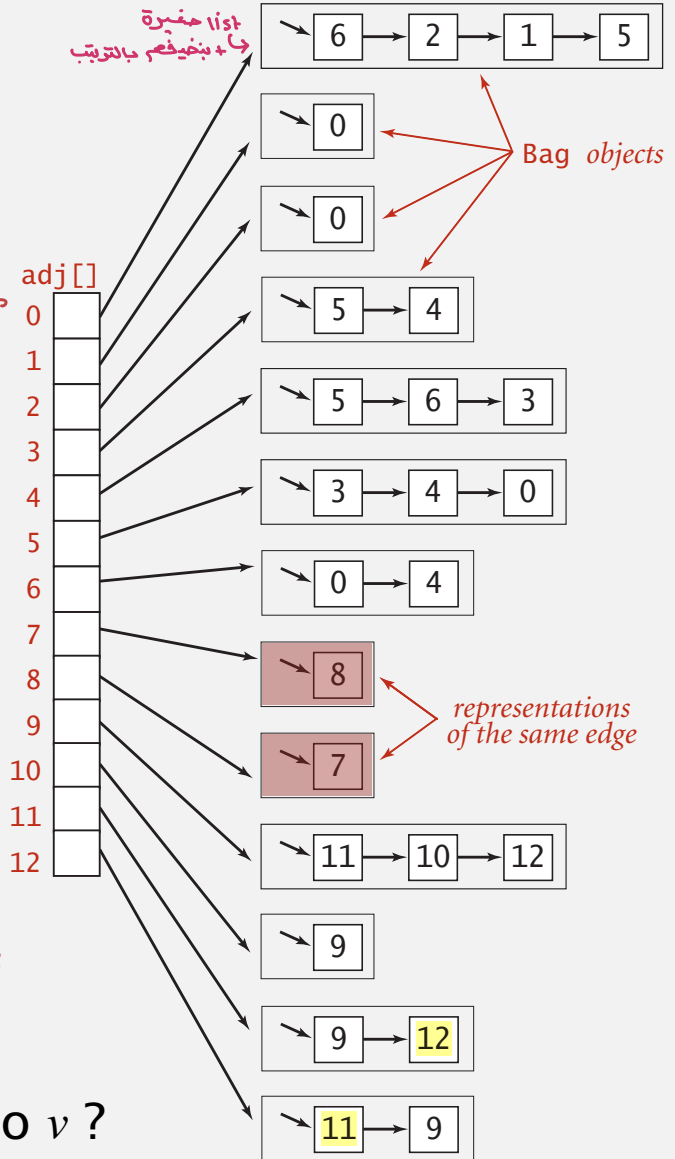
اللاين بينذكر مرتين

ال vertex الاساسية عندي .



linked list + الترتيب غير مهم

الترتيب غير مهم  
بنيصفر بالترتيب



لان تبدلها  
Space complexity  $O(V^2)$

Q. How long to iterate over vertices adjacent to  $v$  ?

degree (v)

# Graph representations

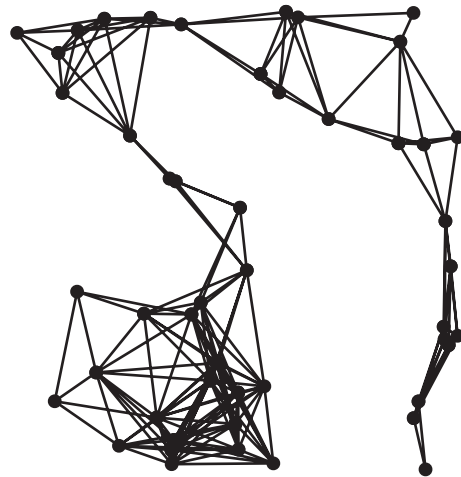
In practice. Use adjacency-lists representation.

- Algorithms based on iterating over vertices adjacent to  $v$ .
- Real-world graphs tend to be **sparse**.

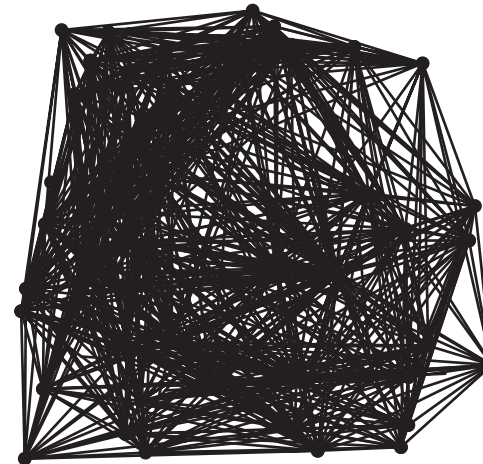
بیکون علاقہ کثیر بالرحمہ  
کثرتہ خطوط!  
نہدہ کثیرہ علاقہ اتلا

huge number of vertices,  
small average vertex degree

sparse ( $E = 200$ )



کثرتہ  
dense ( $E = 1000$ )  
نہدہ کثیرہ علاقہ کثیر.



Two graphs ( $V = 50$ )

# Graph representations

In practice. Use adjacency-lists representation.

- Algorithms based on iterating over vertices adjacent to  $v$ .
- Real-world graphs tend to be **sparse**.

huge number of vertices,  
small average vertex degree

representation	space	add edge	edge between $v$ and $w$ ?	iterate over vertices adjacent to $v$ ?
list of edges	$E$	1	$O(E)$	$O(E)$
adjacency matrix	$V^2$	$1^*$	1	$O(V)$
adjacency lists	$E + V$	1	$degree(v)$	$degree(v)$

\* disallows parallel edges

# Adjacency-list graph representation: Java implementation

```
public class Graph  
{
```

```
    private final int V;  
    private Bag<Integer>[] adj;
```

← adjacency lists  
( using Bag data type )

```
    public Graph(int V)  
    {
```

```
        this.V = V;  
        adj = (Bag<Integer>[]) new Bag[V];  
        for (int v = 0; v < V; v++)  
            adj[v] = new Bag<Integer>();  
    }
```

← create empty graph  
with V vertices

```
        creat ← linked list → adj[v] = new Bag<Integer>();  
    }
```

```
    public void addEdge(int v, int w)
```

```
    {  
        undirect → الحفا الفخمين  
        adj[v].add(w);  
        adj[w].add(v);  
    }
```

← add edge v-w  
(parallel edges and  
self-loops allowed)

```
    public Iterable<Integer> adj(int v)  
    { return adj[v]; }  
}
```

← iterator for vertices adjacent to v



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## 4.1 UNDIRECTED GRAPHS

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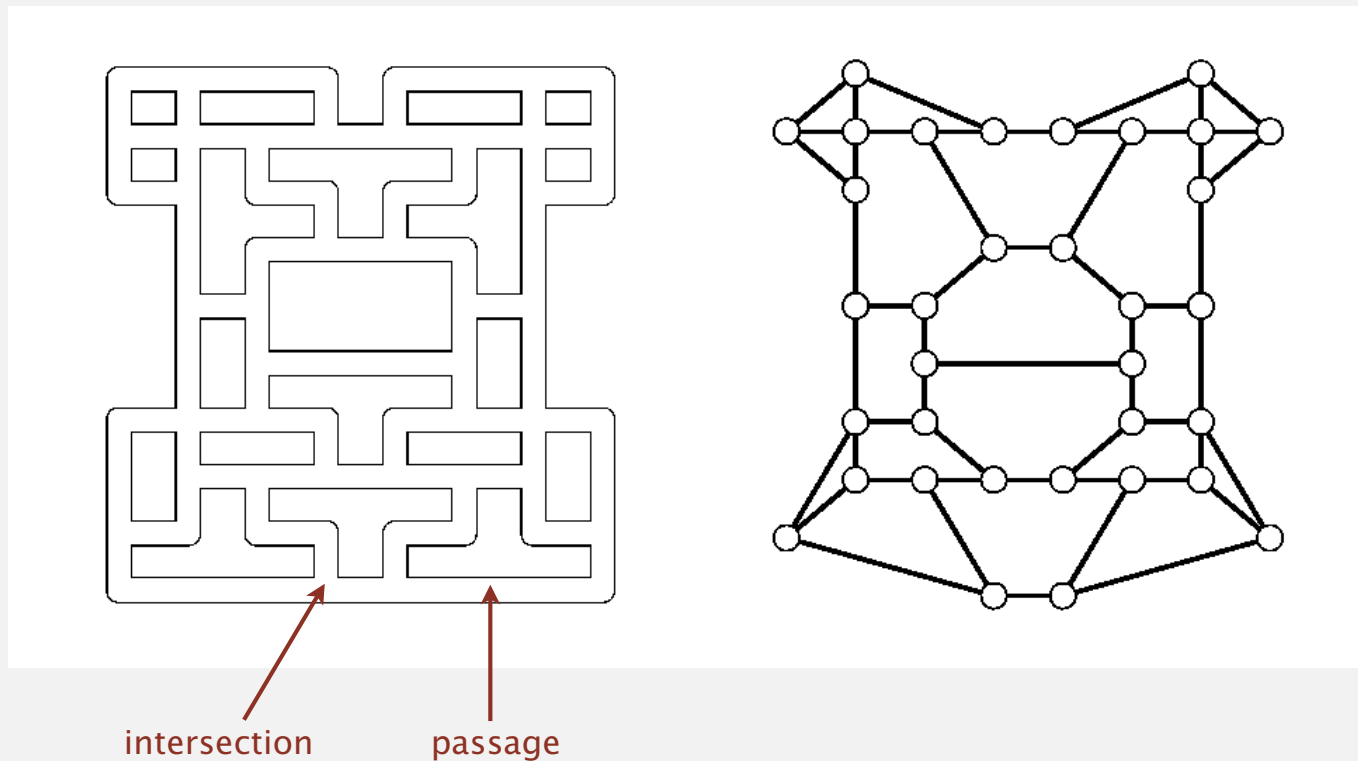
- ▶ *introduction*
- ▶ *graph API*
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- ▶ *connected components*
- ▶ *challenges*

# Maze exploration

---

## Maze graph. back track

- Vertex = intersection.
- Edge = passage.



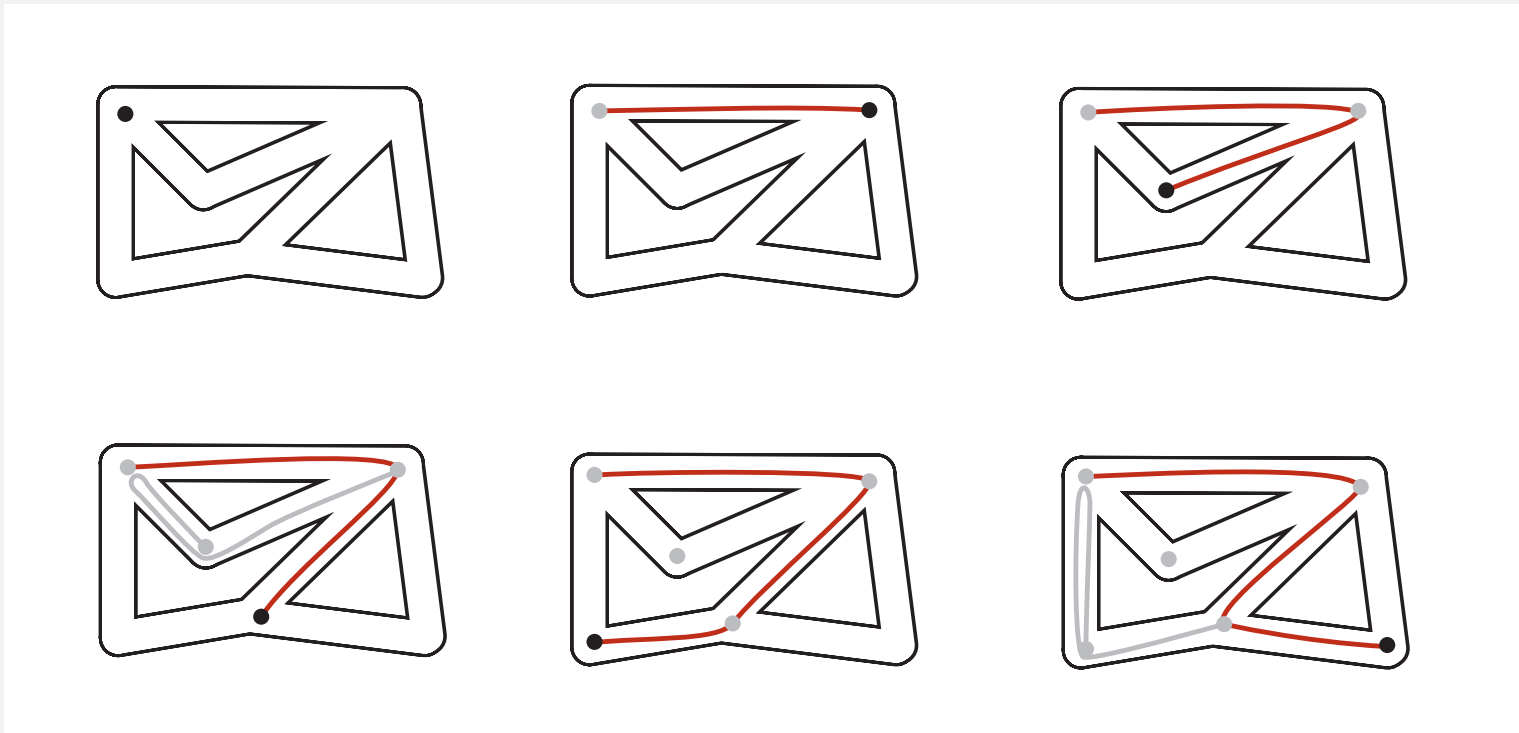
**Goal.** Explore every intersection in the maze.

# Trémaux maze exploration

---

## Algorithm.

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options.



# Trémaux maze exploration

---

## Algorithm.

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options.

**First use?** Theseus entered Labyrinth to kill the monstrous Minotaur; Ariadne instructed Theseus to use a ball of string to find his way back out.



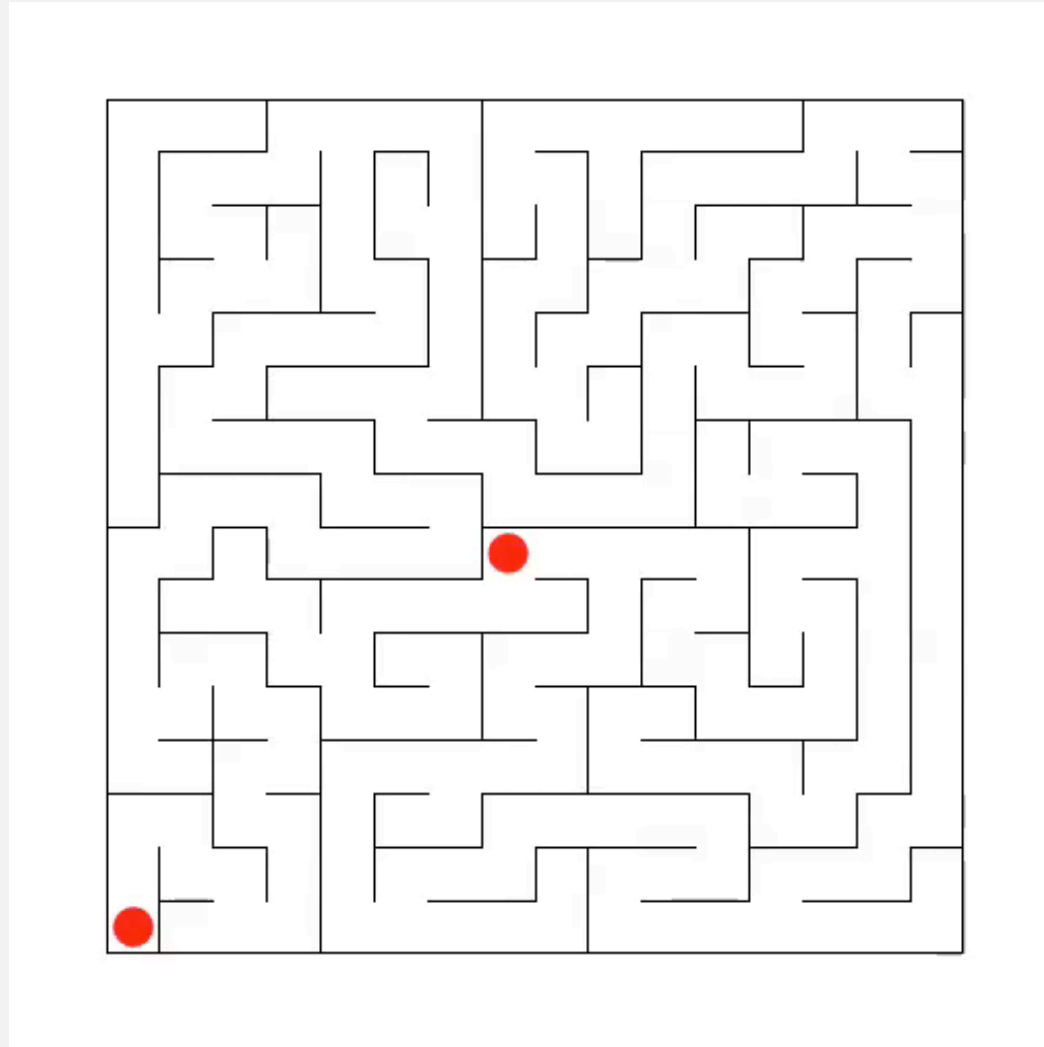
The Labyrinth (with Minotaur)



Claude Shannon (with Theseus mouse)

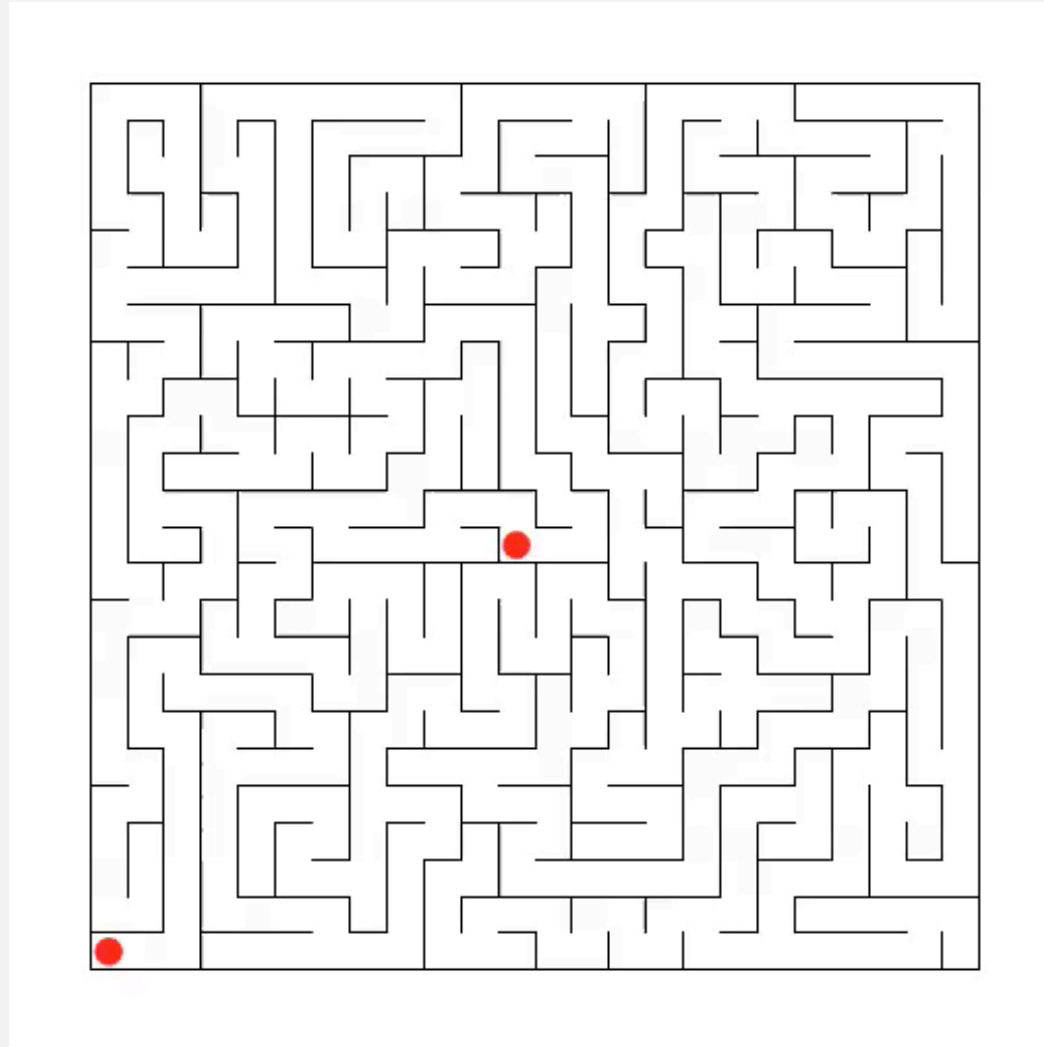
# Maze exploration: easy

---



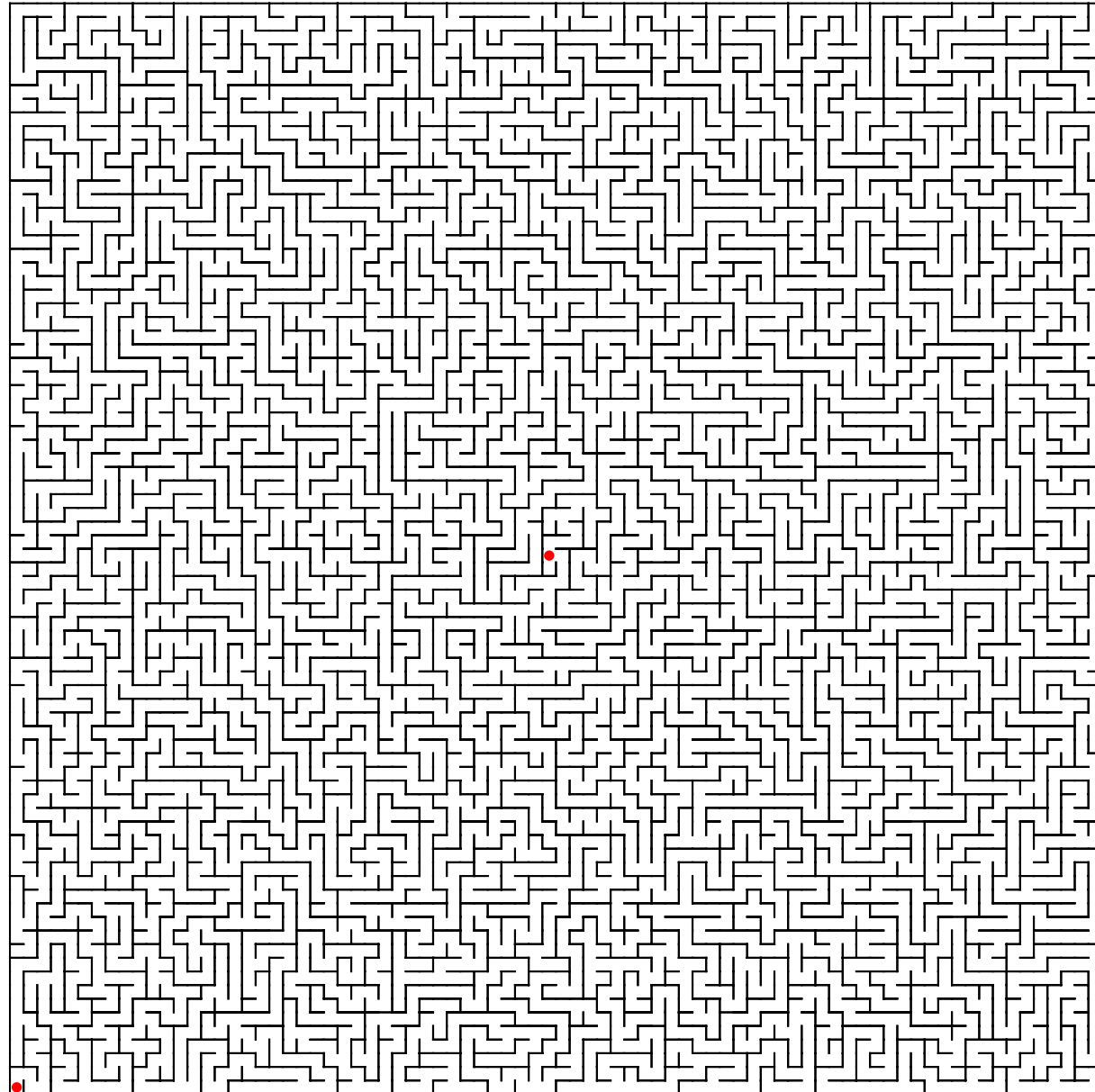
# Maze exploration: medium

---



# Maze exploration: challenge for the bored

---



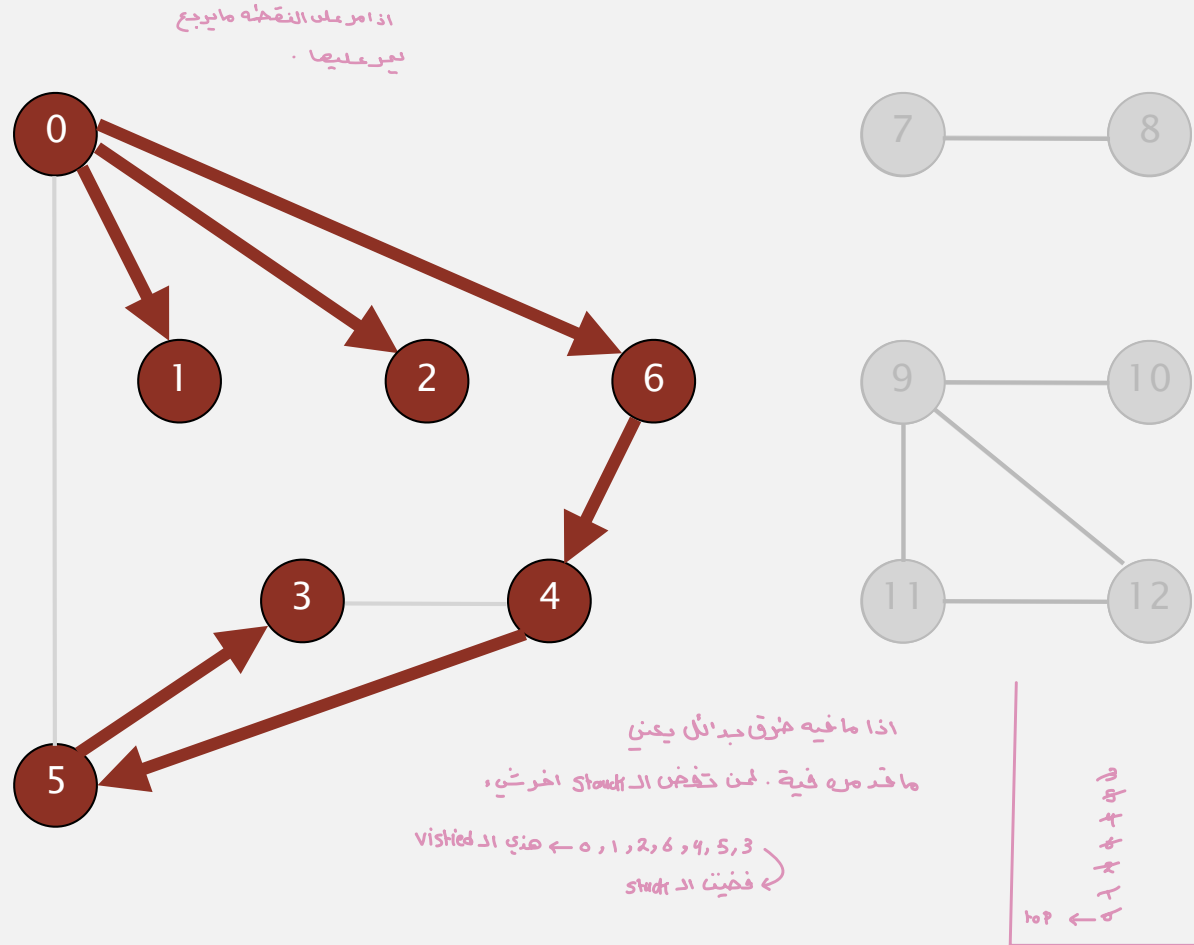




# Depth-first search demo

To visit a vertex  $v$  :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent to  $v$ .



v	marked[]	edgeTo[]
0	T	-
1	T	0
2	T	0
3	T	5
4	T	6
5	T	4
6	T	0
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	-

vertices reachable from 0

# Design pattern for graph processing

---

**Design pattern.** Decouple graph data type from graph processing.

- Create a Graph object.
- Pass the Graph to a graph-processing routine.
- Query the graph-processing routine for information.

```
public class Paths
```

```
    Paths(Graph G, int s)
```

*find paths in G from source s*

```
    boolean hasPathTo(int v)
```

*is there a path from s to v?*

```
    Iterable<Integer> pathTo(int v)
```

*path from s to v; null if no such path*

```
Paths paths = new Paths(G, s);  
for (int v = 0; v < G.V(); v++)  
    if (paths.hasPathTo(v))  
        StdOut.println(v);
```

← print all vertices  
connected to s

# Depth-first search: data structures

---

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent to  $v$ .

Data structures.

- Boolean array `marked[]` to mark visited vertices.
- Integer array `edgeTo[]` to keep track of paths.  
(`edgeTo[w] == v`) means that edge  $v-w$  taken to visit  $w$  for first time
- Function-call stack for recursion.

# Depth-first search: Java implementation

```
public class DepthFirstPaths
{
    private boolean[] marked;
    private int[] edgeTo;
    private int s;
```

marked[v] = true  
if v connected to s

edgeTo[v] = previous  
vertex on path from s to v

```
    public DepthFirstPaths(Graph G, int s)
    {
        ...
        dfs(G, s);
    }
```

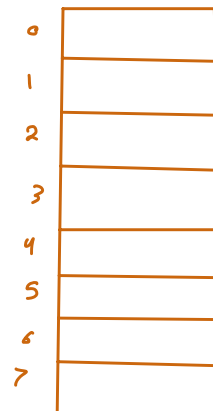
initialize data structures

find vertices connected to s

size : v

```
    private void dfs(Graph G, int v)
    {
        → marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w])
            {
                dfs(G, w);
                edgeTo[w] = v;
            }
    }
}
```

recursive DFS does the work



# Depth-first search: properties

**Proposition.** DFS marks all vertices connected to  $s$  in time proportional to the sum of their degrees (plus time to initialize the `marked[]` array).

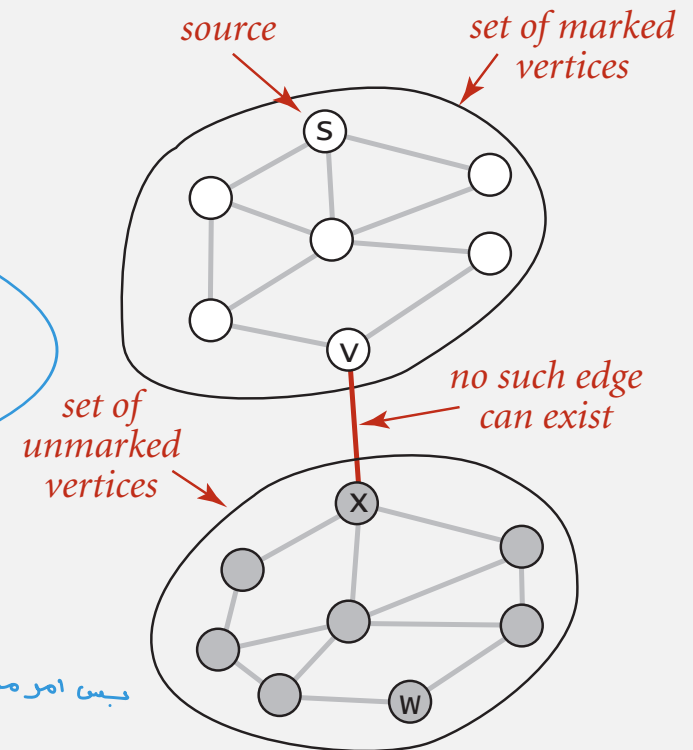
**Pf.** [correctness]

- If  $w$  marked, then  $w$  connected to  $s$  (why?)
- If  $w$  connected to  $s$ , then  $w$  marked.  
(if  $w$  unmarked, then consider last edge on a path from  $s$  to  $w$  that goes from a marked vertex to an unmarked one).

← في ما معناه : اذا بس خلصت وكان عندي وحدة (mark) في مريوحة بطريقه  
معنى مع ال (S) الي جيت فيها . واذا عندي وحدة (unmarked) مناته ما فيه (edge) يوصل منها .

**Pf.** [running time]

Each vertex connected to  $s$  is visited once. → بس امره وحدة



# Depth-first search: properties

**Proposition.** After DFS, can check if vertex  $v$  is connected to  $s$  in constant time and can find  $v$ - $s$  path (if one exists) in time proportional to its length.

انا بقدر امرف من النقطه مفتر  
لاي نقطه ثانيه على حسب الـ (Constant) الي طالع  
عندي قد ايش عدد الـ (Path) الي بمر فيهم .

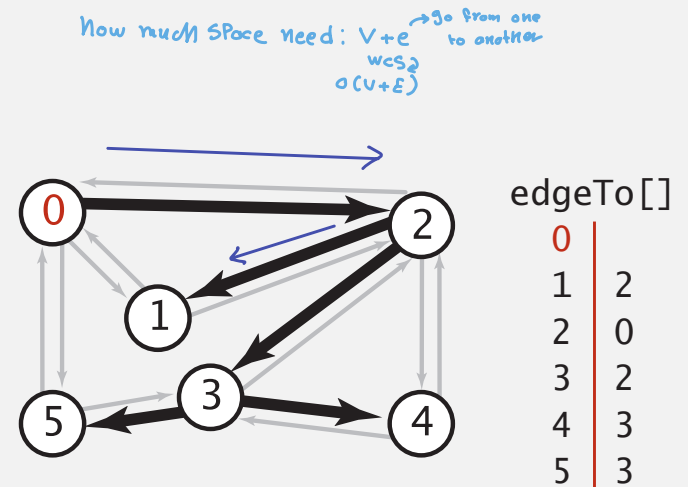
**Pf.** `edgeTo[]` is parent-link representation of a tree rooted at vertex  $s$ .

```
public boolean hasPathTo(int v)
{ return marked[v]; }

public Iterable<Integer> pathTo(int v)
{
    if (!hasPathTo(v)) return null;
    Stack<Integer> path = new Stack<Integer>();
    for (int x = v; x != s; x = edgeTo[x])
        path.push(x);
    path.push(s);
    return path;
}
```

في الـ path فيه path  
unmarked : path

في الـ stack



# Depth-first search application: flood fill

---

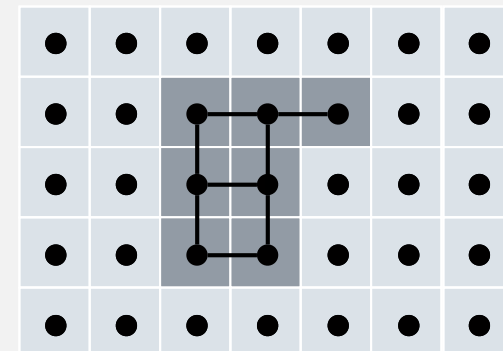
**Challenge.** Flood fill (Photoshop magic wand).

**Assumptions.** Picture has millions to billions of pixels.

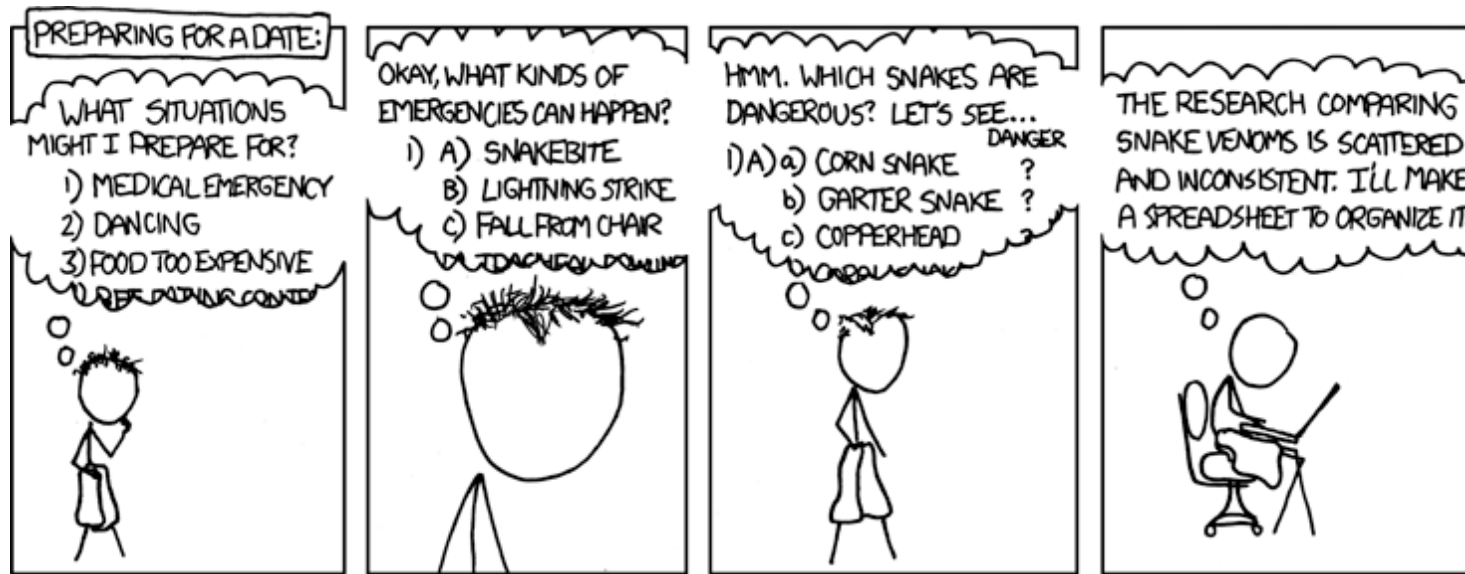


**Solution.** Build a **grid graph** (implicitly).

- Vertex: pixel.
- Edge: between two adjacent gray pixels.
- Blob: all pixels connected to given pixel.



# Depth-first search application: preparing for a date



I REALLY NEED TO STOP USING DEPTH-FIRST SEARCHES.

xkcd

<http://xkcd.com/761/>



<http://algs4.cs.princeton.edu>

## 4.1 UNDIRECTED GRAPHS

---

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Sorted Path →

# Breadth-first search demo → Queue تستخدم ال

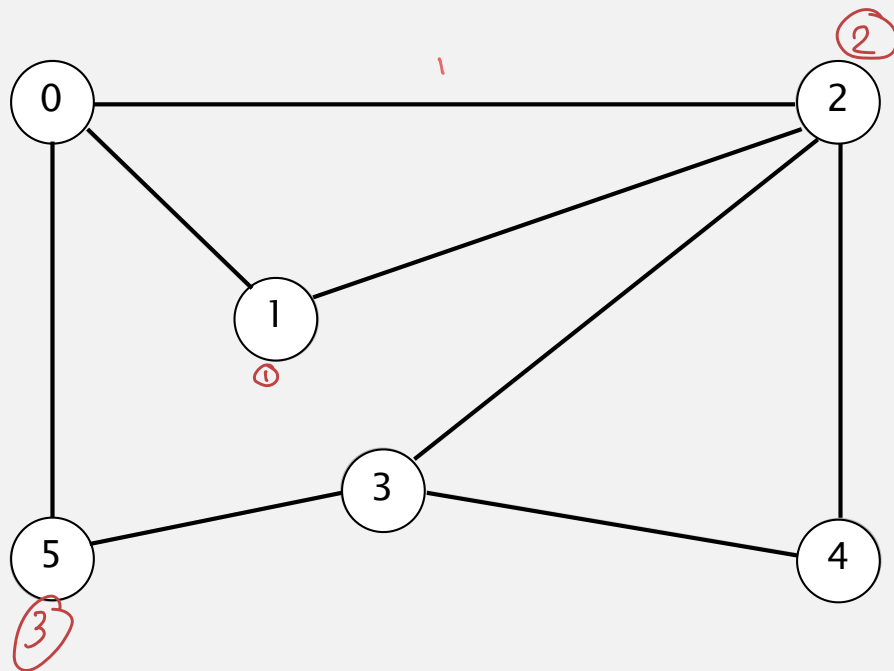
Repeat until **queue** is empty:



- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices adjacent to  $v$  and mark them.

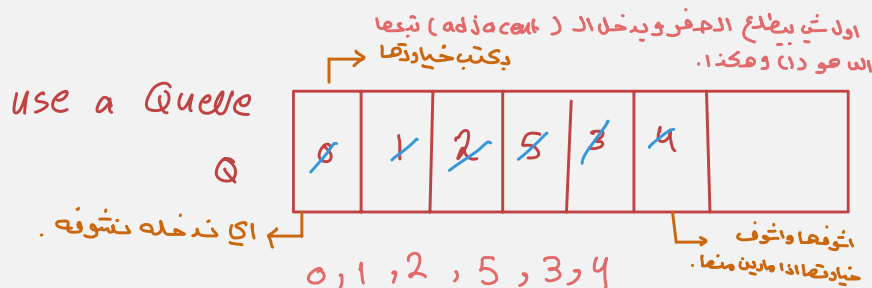
queue : من النقطه ال بيدها اي واحد يدخلها ال ( queue )  
 من اجن اخلها بيفيف كل ال ( Vertices adjacent unmark )

FDS  
Sorted bott



tinyCG.txt

V → 6 ← E  
 8  
 0 5  
 2 4  
 2 3  
 1 2  
 0 1  
 3 4  
 3 5  
 0 2

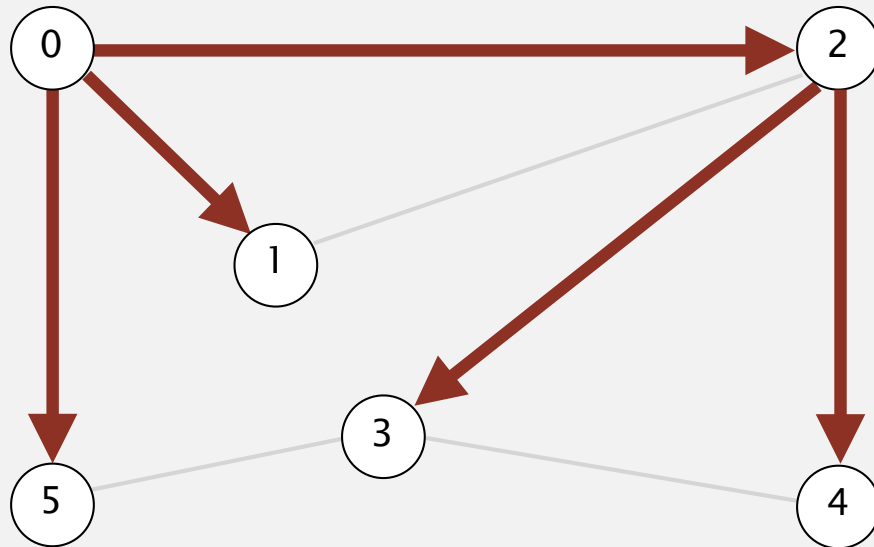


graph G

# Breadth-first search demo

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices adjacent to  $v$  and mark them.



run time:  $O(V+E)$

$v$	edgeTo[]	distTo[]
0	-	0
1	0	1
2	0	1
3	2	2
4	2	2
5	0	1

done

# Breadth-first search

---

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices adjacent to  $v$  and mark them.

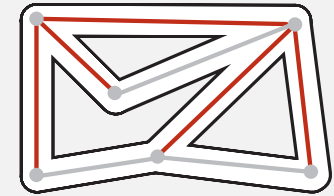
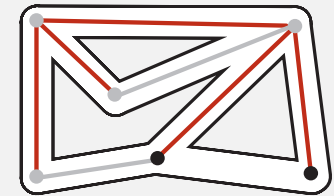
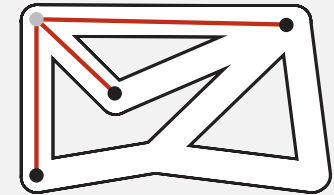
**BFS** (from source vertex  $s$ )

---

**Put  $s$  onto a FIFO queue, and mark  $s$  as visited.**

**Repeat until the queue is empty:**

- **remove the least recently added vertex  $v$**
  - **add each of  $v$ 's unvisited neighbors to the queue, and mark them as visited.**
- 



Sample: ماصيا مكررة

not sample: مكررة

# Breadth-first search: Java implementation

```
public class BreadthFirstPaths
{
    private boolean[] marked;
    private int[] edgeTo;
    private int[] distTo;

    ...

```

```
private void bfs(Graph G, int s) {
    Queue<Integer> q = new Queue<Integer>();
    q.enqueue(s);
    marked[s] = true;
    distTo[s] = 0;

    while (!q.isEmpty()) {
        int v = q.dequeue();
        for (int w : G.adj(v)) {
            if (!marked[w]) {
                q.enqueue(w);
                marked[w] = true;
                edgeTo[w] = v;
                distTo[w] = distTo[v] + 1;
            }
        }
    }
}

```

initialize FIFO queue of vertices to explore

found new vertex w via edge v-w

# Breadth-first search properties

Q. In which order does BFS examine vertices?

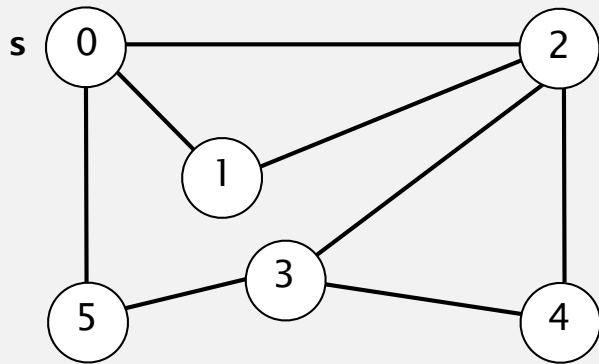
A. Increasing distance (number of edges) from  $s$ .

يمكن الاعتماد على الحروف .

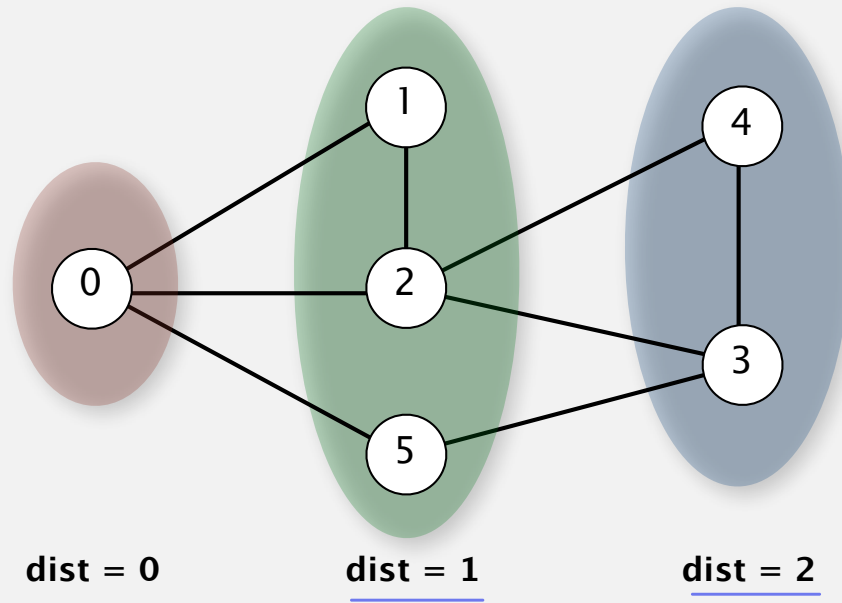
queue always consists of  $\geq 0$  vertices of distance  $k$  from  $s$ , followed by  $\geq 0$  vertices of distance  $k+1$

**Proposition.** In any connected graph  $G$ , BFS computes shortest paths from  $s$  to all other vertices in **time** proportional to  $E+V$ .

مرات : استخدم المسافات من الصغير للكبير : المسافة (1), (2), (3)  
 ممكن استخدم المسافات من الكبير للصغير : المسافة (3), (2), (1)



graph G



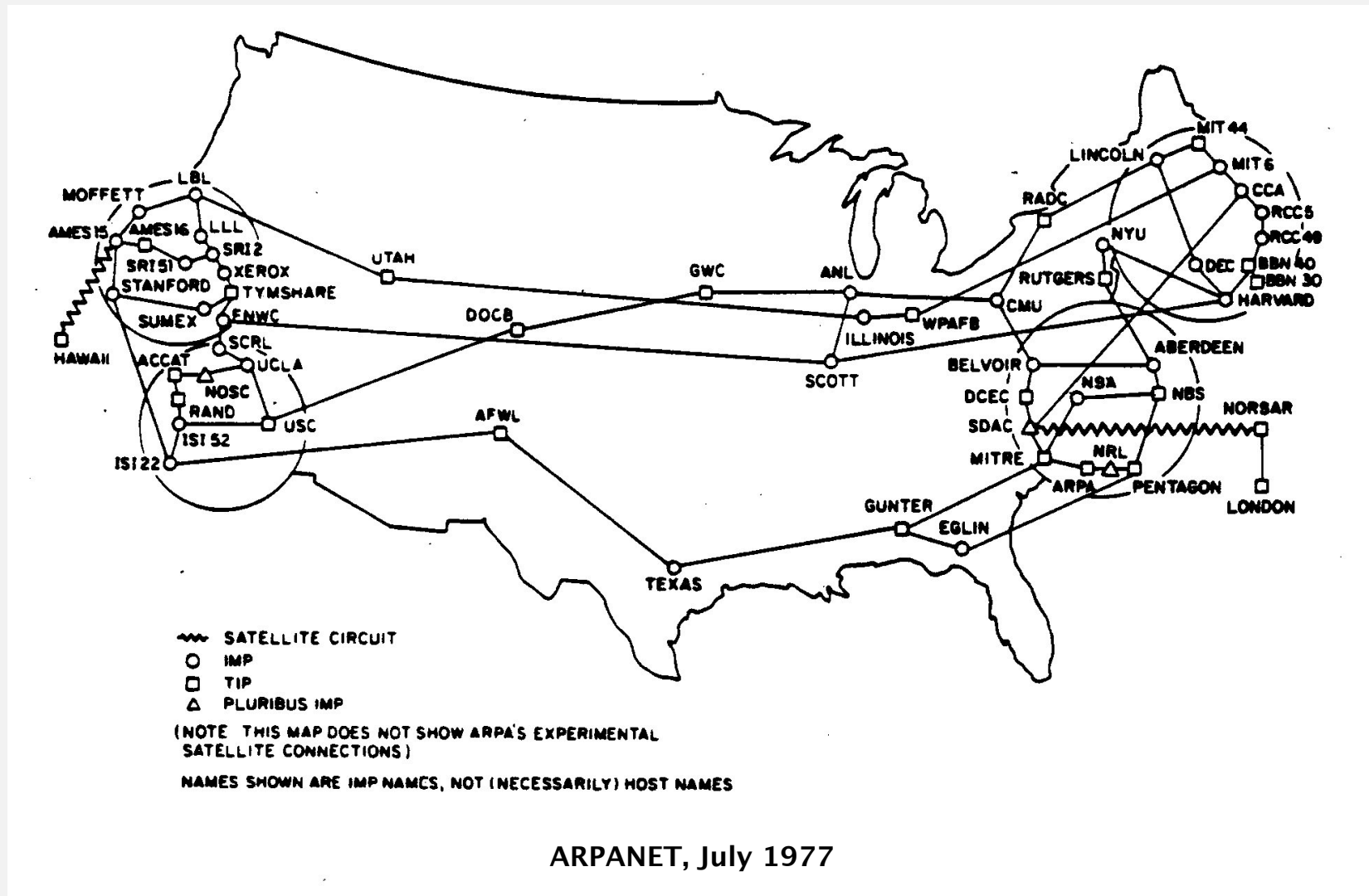
dist = 0

dist = 1

dist = 2

# Breadth-first search application: routing

Fewest number of hops in a communication network.



# Breadth-first search application: Kevin Bacon numbers

The Oracle of Bacon

http://www.oracleofbacon.org/cgi-bin/movie/links?game=0&firstname=Kevin+Bacon

THE ORACLE OF BACON

Help  
Credits  
How it Works  
Contact Us  
Other games »

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Buzz Mauro  
=w/in  
Sweet Dreams (2005)  
=w/in  
Tatiana Ramirez  
=w/in  
Interior de un silencio, El (2005)  
=w/in  
Andres Suarez  
=w/in  
Carlita's Secret (2004)  
=w/in  
Paula Lemes (I)  
=w/in  
Frost/Nixon (2008)  
=w/in  
Kevin Bacon

Kevin Bacon to Buzz Mauro Find link More options >>

<http://oracleofbacon.org>



Endless Games board game

New 2 Degrees

Uma Thurman  
acted in

Be Cool (2005) 1°  
with

Scott Adsit  
who acted in

The Informant! (2009) 2°  
with

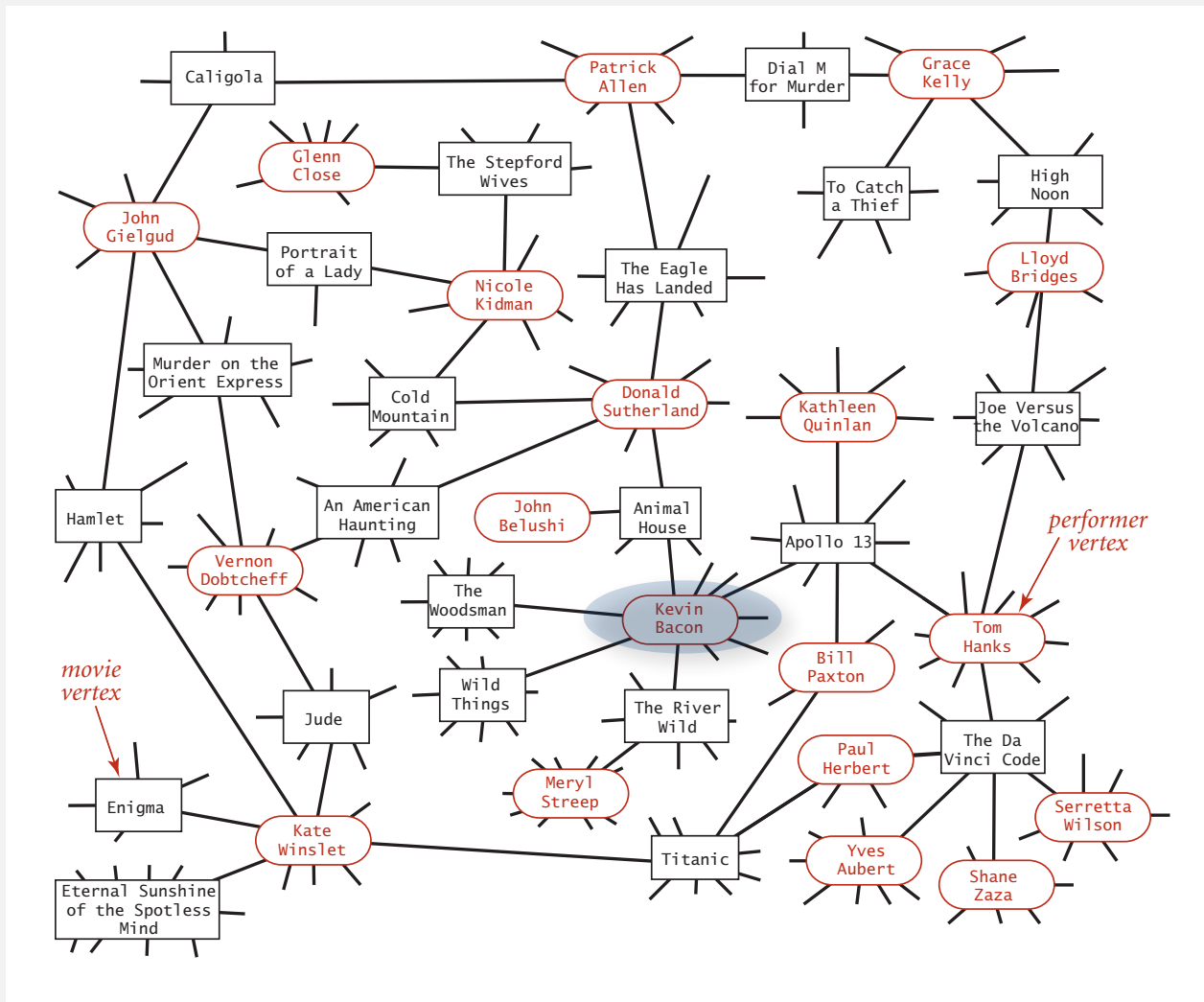
Matt Damon

Lookup Trivia Guess Degrees Scoreboard

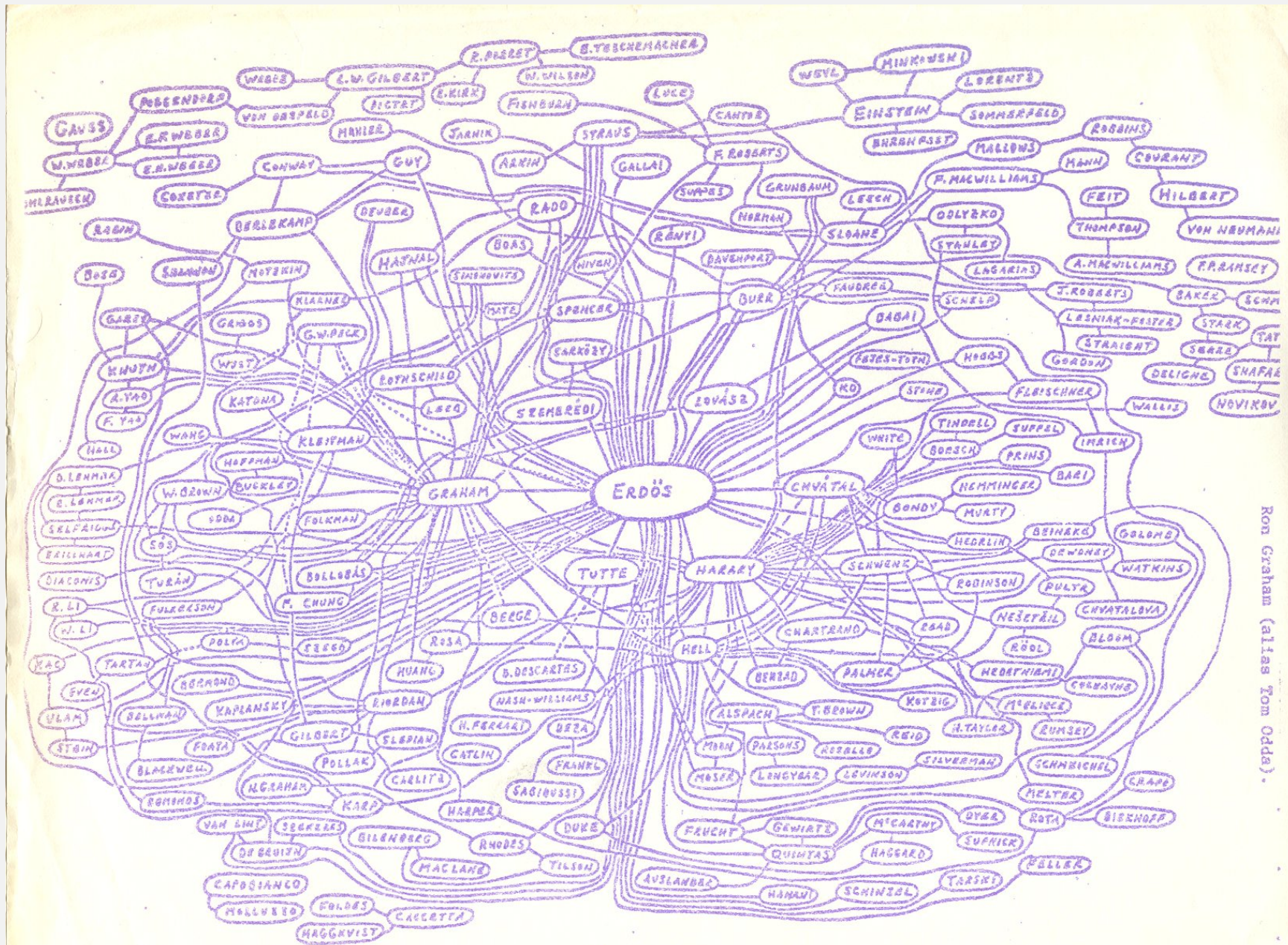
SixDegrees iPhone App

# Kevin Bacon graph

- Include one vertex for each performer **and** one for each movie.
- Connect a movie to all performers that appear in that movie.
- Compute shortest path from  $s = \text{Kevin Bacon}$ .



# Breadth-first search application: Erdős numbers



hand-drawing of part of the Erdős graph by Ron Graham



<http://algs4.cs.princeton.edu>

## 4.1 UNDIRECTED GRAPHS

---

- ▶ *introduction*
- ▶ *graph API*
- ▶ *depth-first search*
- ▶ *breadth-first search*
- ▶ *connected components*
- ▶ *challenges*

# Connectivity queries

---

Def. Vertices  $v$  and  $w$  are **connected** if there is a path between them.



Goal. Preprocess graph to answer queries of the form *is  $v$  connected to  $w$ ?* in **constant time**.

```
public class CC
```

```
    CC(Graph G)
```

*find connected components in  $G$*

```
    boolean connected(int v, int w)
```

*are  $v$  and  $w$  connected?*

```
    int count()
```

*number of connected components*

```
    int id(int v)
```

*component identifier for  $v$   
(between 0 and  $\text{count}() - 1$ )*

Union-Find? Not quite.

Depth-first search. Yes. [next few slides]

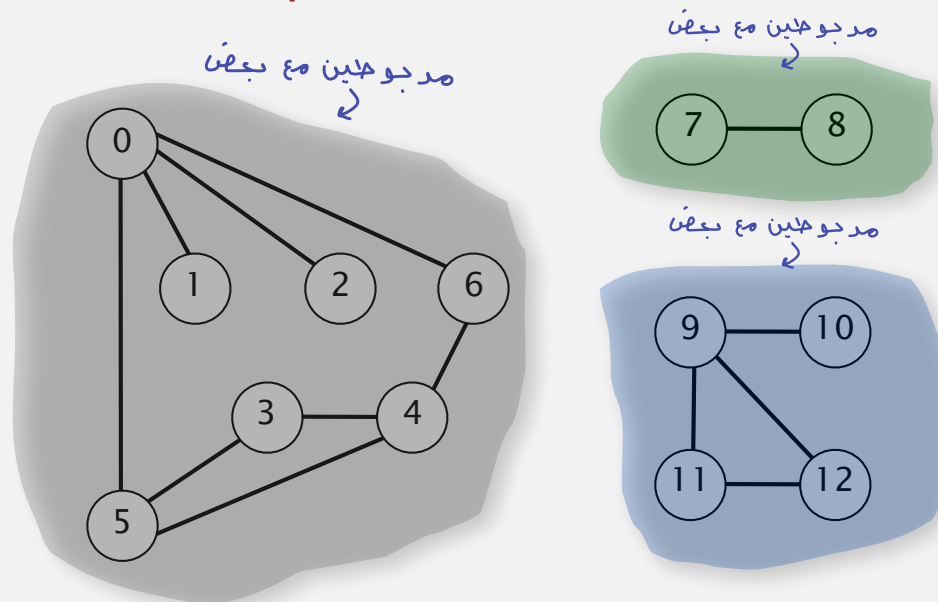
# Connected components

The relation "is connected to" is an **equivalence relation**:

- Reflexive:  $v$  is connected to  $v$ .
- Symmetric: if  $v$  is connected to  $w$ , then  $w$  is connected to  $v$ .
- Transitive: if  $v$  connected to  $w$  and  $w$  connected to  $x$ , then  $v$  connected to  $x$ .

انواع العلاقات

**Def.** A **connected component** is a maximal set of connected vertices.



3 connected components

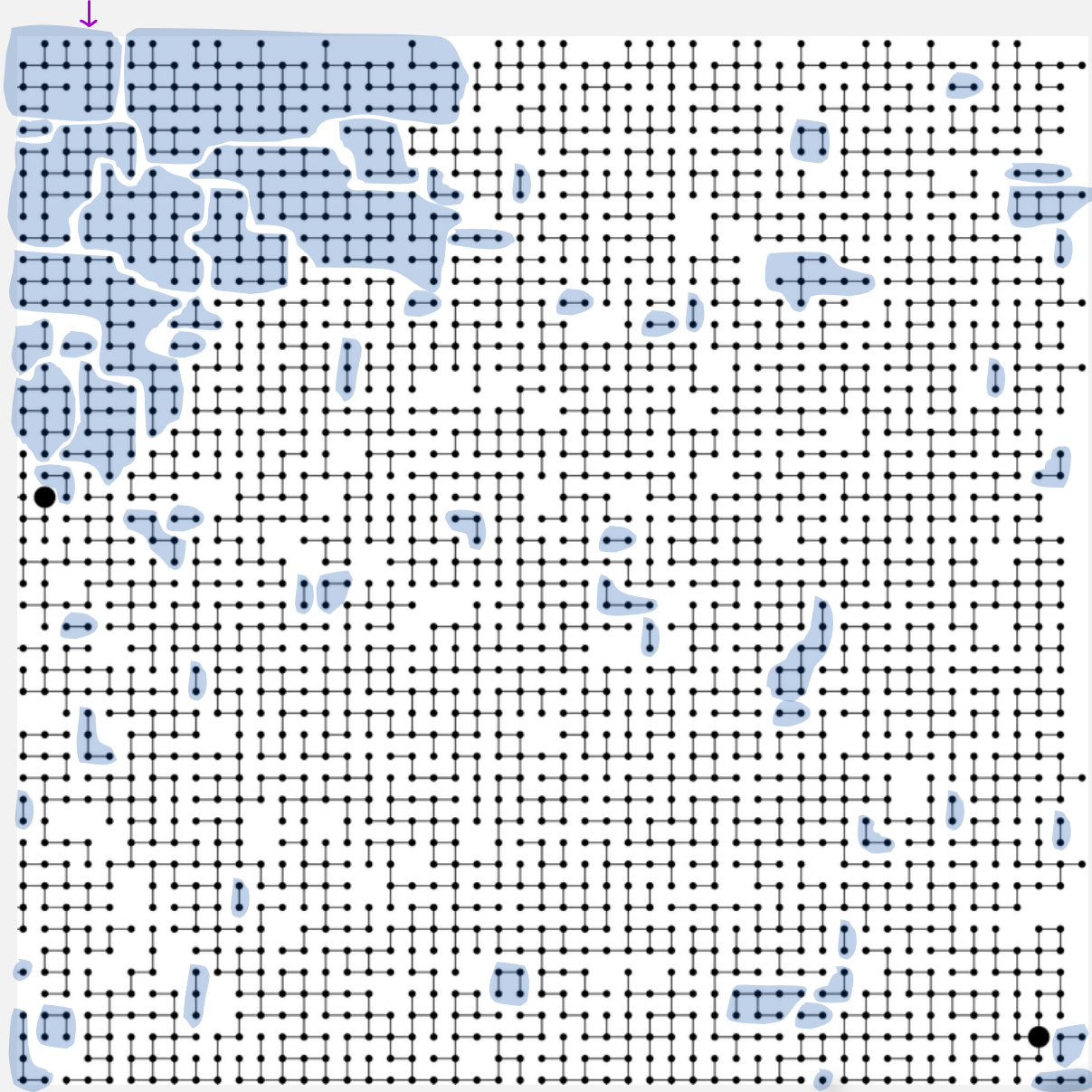
v	id[]
0	0
1	0
2	0
3	0
4	0
5	0
6	0
7	1
8	1
9	2
10	2
11	2
12	2

**Remark.** Given connected components, can answer queries in constant time.

# Connected components

---

Def. A **connected component** is a maximal set of connected vertices.



63 connected components

# Connected components

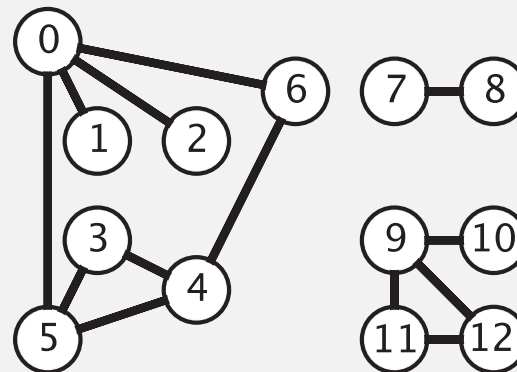
Goal. Partition vertices into connected components.

## Connected components

Initialize all vertices  $v$  as unmarked.

يعني راح ابدا من الامهر وبشوف  
انه بيوصل لكل حذول وبروح ادور عليه ثاني  
ماهار (True) وبشوف الـ (Vertices) الي مرتبطين  
فيه .

For each unmarked vertex  $v$ , run DFS to identify all vertices discovered as part of the same component.



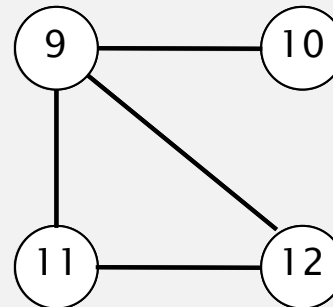
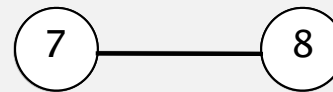
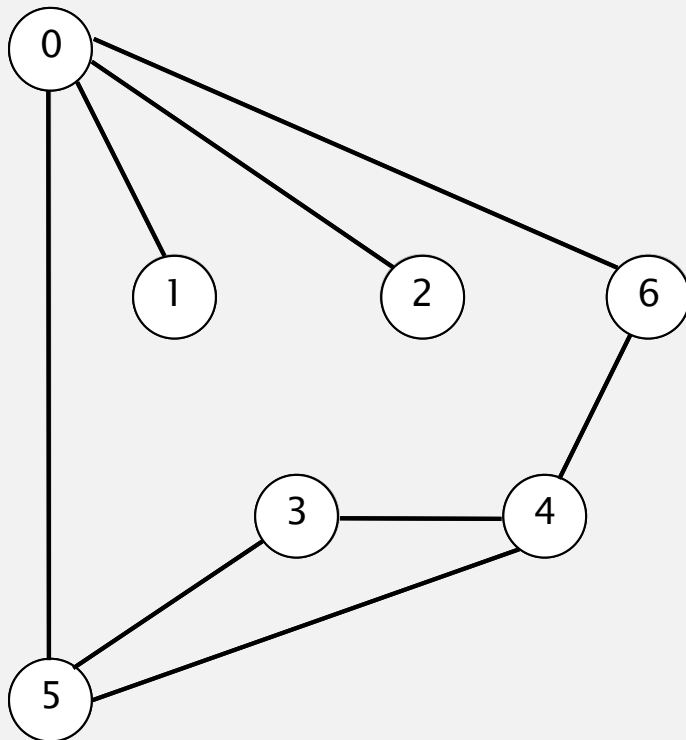
tinyG.txt

```
V → 13  
13 ← E  
0 5  
4 3  
0 1  
9 12  
6 4  
5 4  
0 2  
11 12  
9 10  
0 6  
7 8  
9 11  
5 3
```

# Connected components demo

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent to  $v$ .



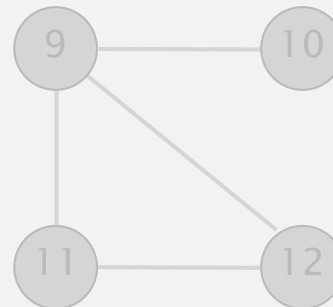
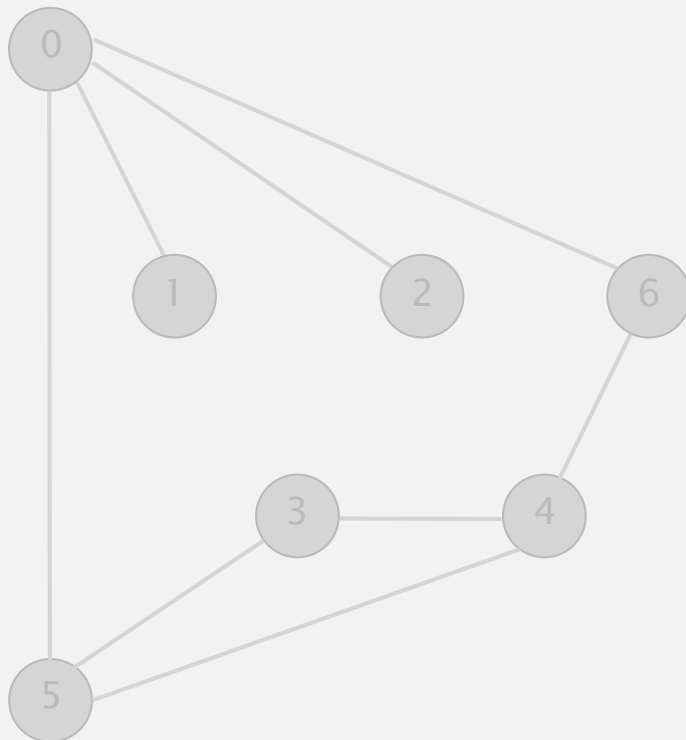
$v$	marked[]	id[]
0	F	-
1	F	-
2	F	-
3	F	-
4	F	-
5	F	-
6	F	-
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	-

graph G

# Connected components demo

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent to  $v$ .



$v$	marked[]	id[]
0	T	0
1	T	0
2	T	0
3	T	0
4	T	0
5	T	0
6	T	0
7	T	1
8	T	1
9	T	2
10	T	2
11	T	2
12	T	2

done

# Finding connected components with DFS

```
public class CC
{
    private boolean[] marked;
    private int[] id;
    private int count;

    public CC(Graph G)
    {
        marked = new boolean[G.V()];
        id = new int[G.V()];
        for (int v = 0; v < G.V(); v++)
        {
            if (!marked[v])
            {
                dfs(G, v);
                count++;
            }
        }
    }

    public int count()
    public int id(int v)
    public boolean connected(int v, int w)
    private void dfs(Graph G, int v)
}
```

id[v] = id of component containing v  
number of components

run DFS from one vertex in  
each component

see next slide

## Finding connected components with DFS (continued)

---

```
public int count()
{ return count; }
```

← number of components

```
public int id(int v)
{ return id[v]; }
```

← id of component containing v

```
public boolean connected(int v, int w)
{ return id[v] == id[w]; }
```

← v and w connected iff same id

```
private void dfs(Graph G, int v)
{
    marked[v] = true;
    id[v] = count;
    for (int w : G.adj(v))
        if (!marked[w])
            dfs(G, w);
}
```

← all vertices discovered in  
same call of dfs have same id

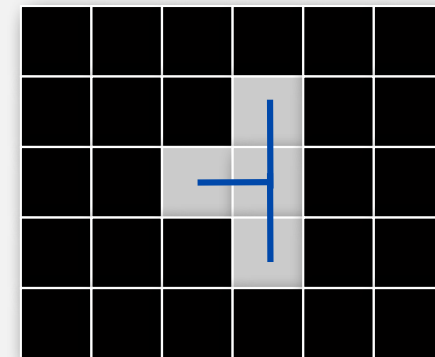
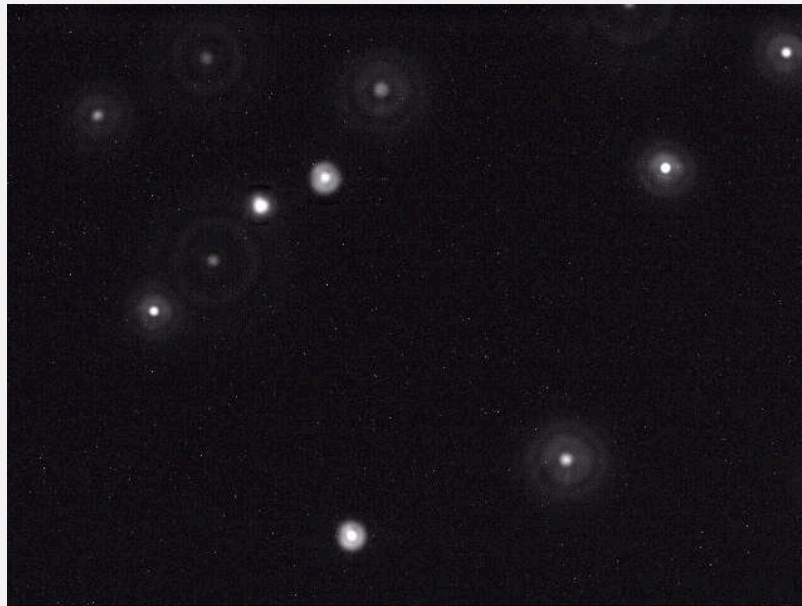
# Connected components application: particle detection

---

**Particle detection.** Given grayscale image of particles, identify "blobs."

- Vertex: pixel.
- Edge: between two adjacent pixels with grayscale value  $\geq 70$ .
- Blob: connected component of 20-30 pixels.

black = 0  
white = 255



**Particle tracking.** Track moving particles over time.

# Graph traversal summary

---

BFS and DFS enables efficient solution of many (but not all) graph problems.

problem	BFS	DFS	time
path between s and t	✓	✓	$E + V$
shortest path between s and t	✓		$E + V$
connected components	✓	✓	$E + V$
✗ biconnected components		✓	$E + V$
✗ cycle	✓	✓	$E + V$
✗ Euler cycle		✓	$E + V$
✗ Hamilton cycle			$2^{1.657 V}$
✗ bipartiteness	✓	✓	$E + V$
✗ planarity		✓	$E + V$
✗ graph isomorphism			$2^{c\sqrt{V \log V}}$